

2D-RC: Two-Dimensional Neural Network Approach for OTFS Symbol Detection

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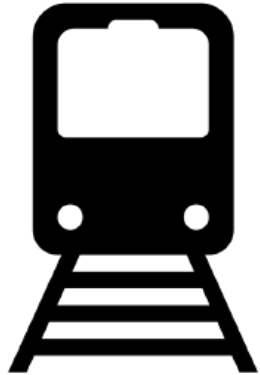
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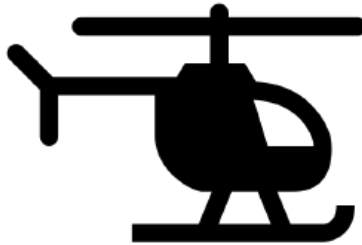


High Mobility Scenarios

- High mobility scenarios



High speed train



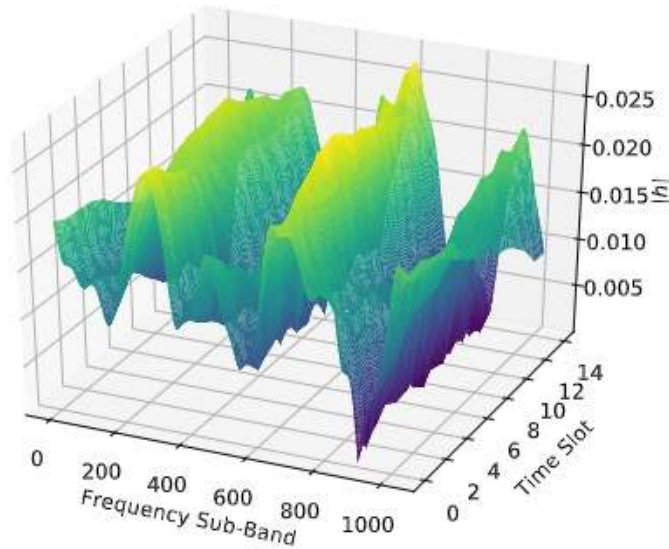
Aircraft-to-ground communication



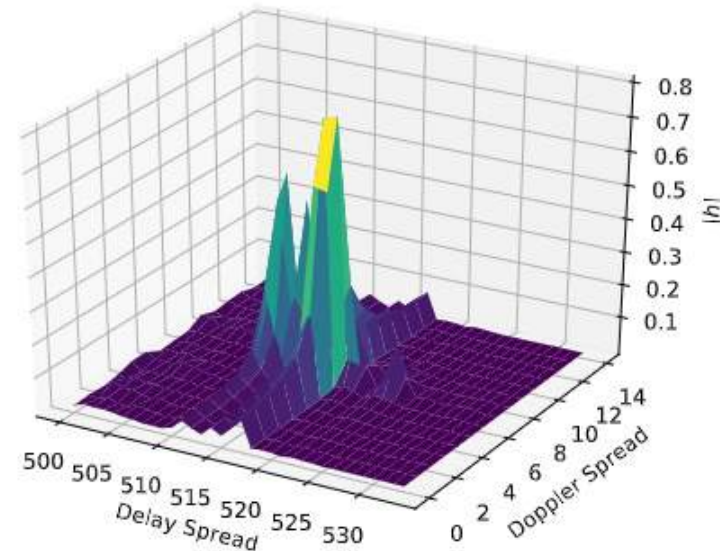
Unmanned aerial vehicle (UAV)
communication systems

Orthogonal Time Frequency Space (OTFS)

- Orthogonal time frequency space (OTFS)
 - Transmit the information symbols in the delay–Doppler domain
 - Less channel variation in the delay–Doppler domain

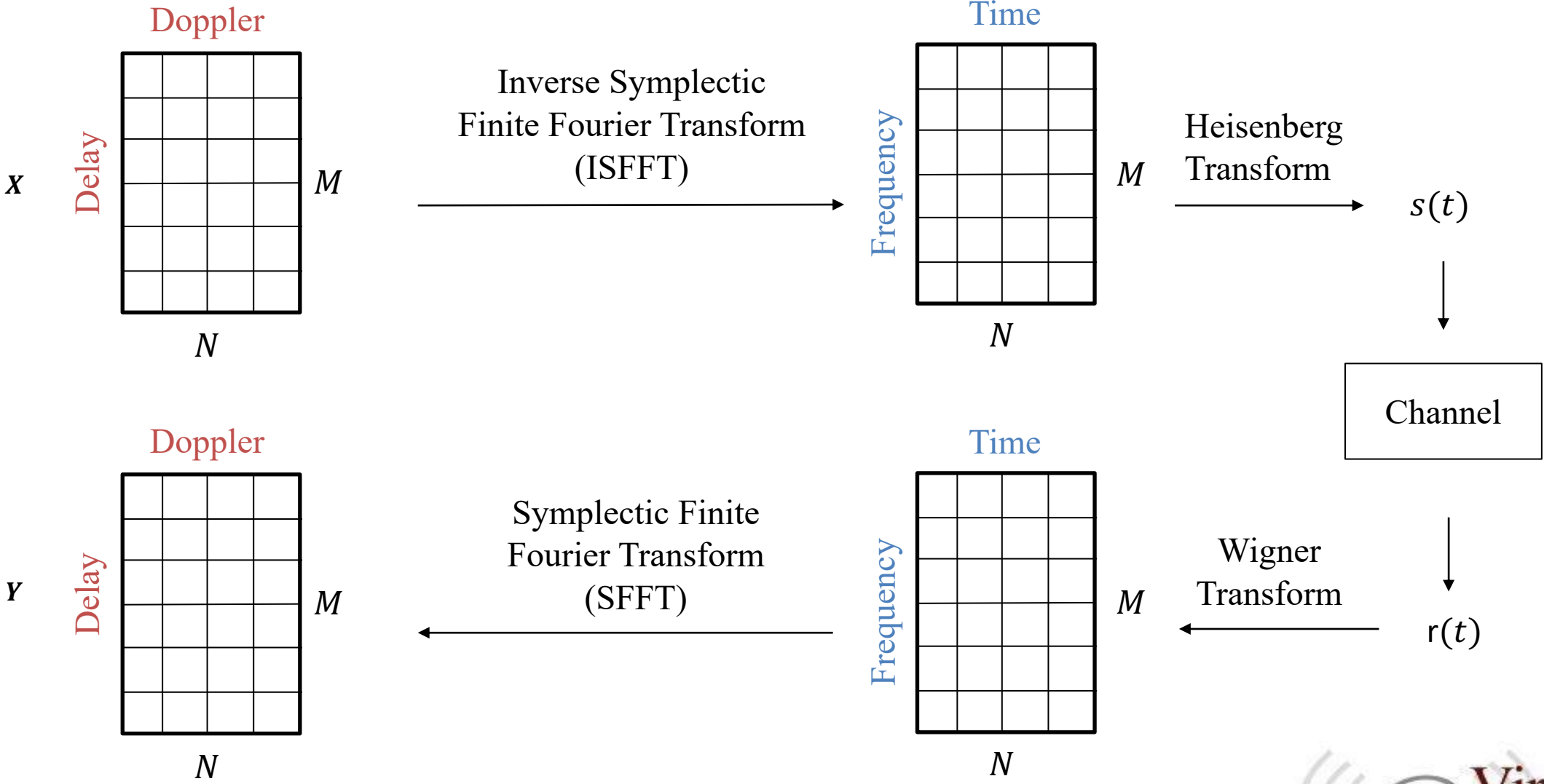


Time-Frequency Channel Representation



Delay-Doppler Channel Representation

The Problem: Symbol Detection in the OTFS System



Existing Work for OTFS Symbol Detection

- Existing work for symbol detection in the OTFS system

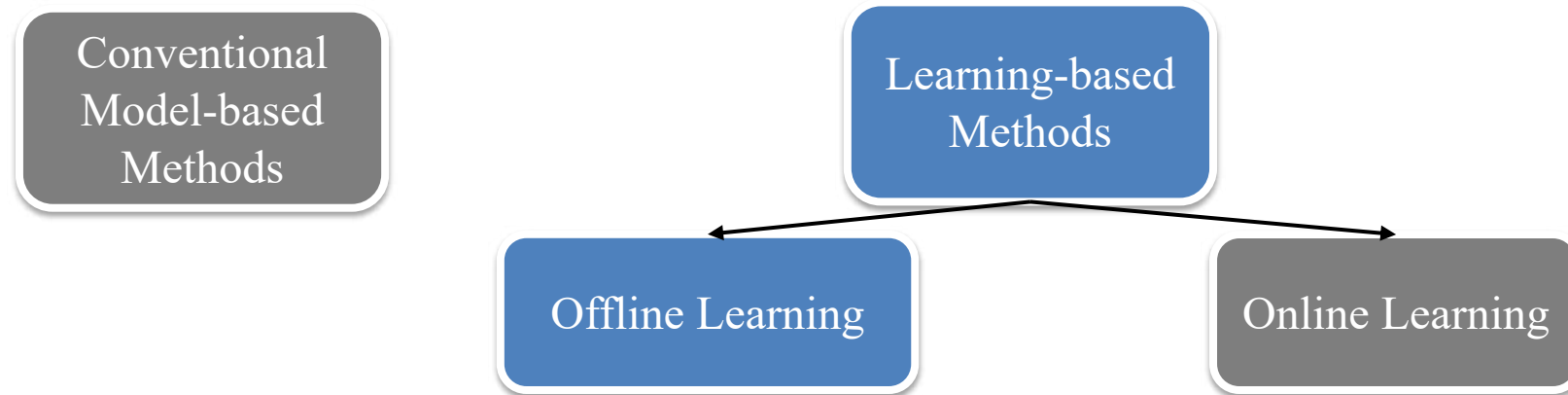
Conventional
Model-based
Methods

Learning-based
Methods

- Explicit system modeling
- Channel state information (CSI) estimation

Existing Work for OTFS Symbol Detection

- Existing work for symbol detection in the OTFS system



- Offline training
 - Large amount of offline training data
 - Long training time
- Online deployment
- Issue
 - Uncertainty in generalization

Generalization Issue of Offline Learning

- Uncertainty of generalization – dynamic setups in NextG ^[1]
 - Mismatches between offline training and online deployment

System configuration
mismatch

E.g., subcarrier spacing,
antenna configurations

Scenario mismatch

E.g., outdoor vs indoor,
urban vs rural

Operation adaptations
mismatch

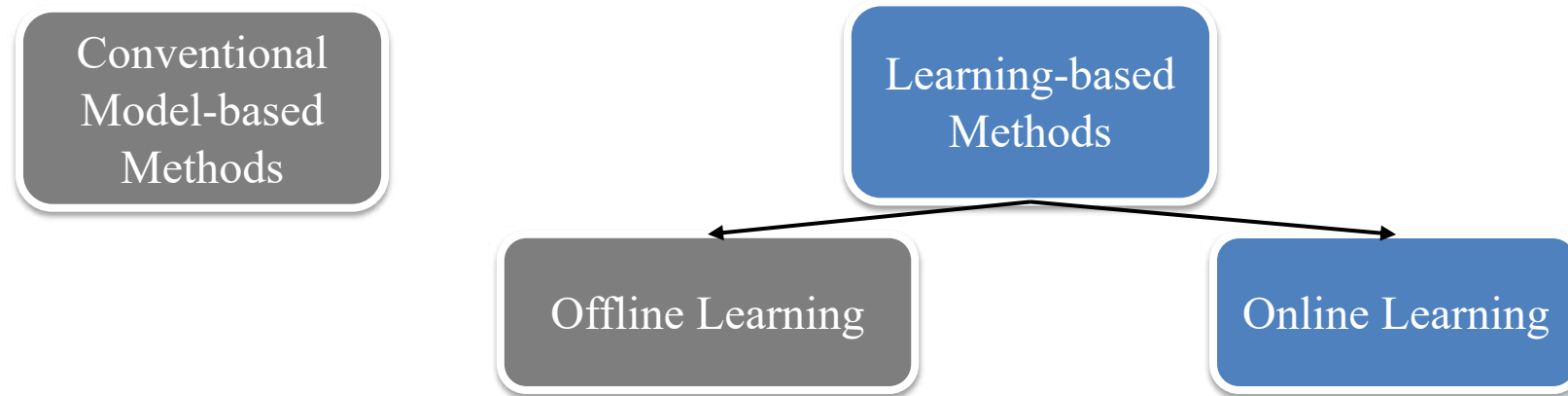
E.g., link/rank adaptation,
scheduling

- Hard to ensure robust generalization across all the cases
- Heterogeneous nature in timescales:
 - Operation adaptations occur on a 5G slot basis (sub-millisecond)

[1] J. Xu, S. Jere, Y. Song, Y. Kao, L. Zheng, and L. Liu. "Learning at the Speed of Wireless: Online Real-Time Learning for AI-Enabled MIMO in NextG.", IEEE Communication Magazine, 2024.

Existing Work for OTFS Symbol Detection

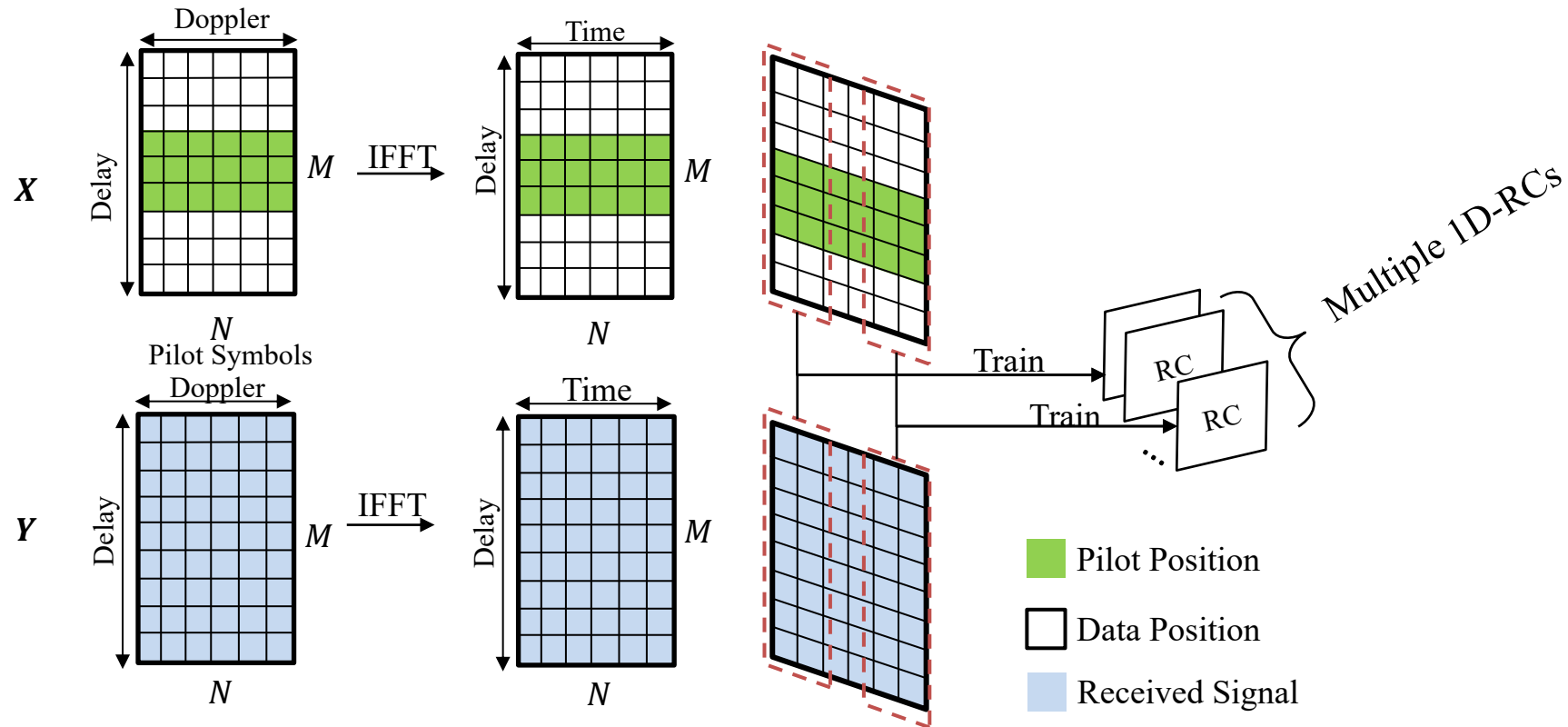
- Existing work for symbol detection in the OTFS system



- Online training
 - Train with only over-the-air (OTA) training pilots within the 5G slot
- Online testing
 - Test within the same 5G slot

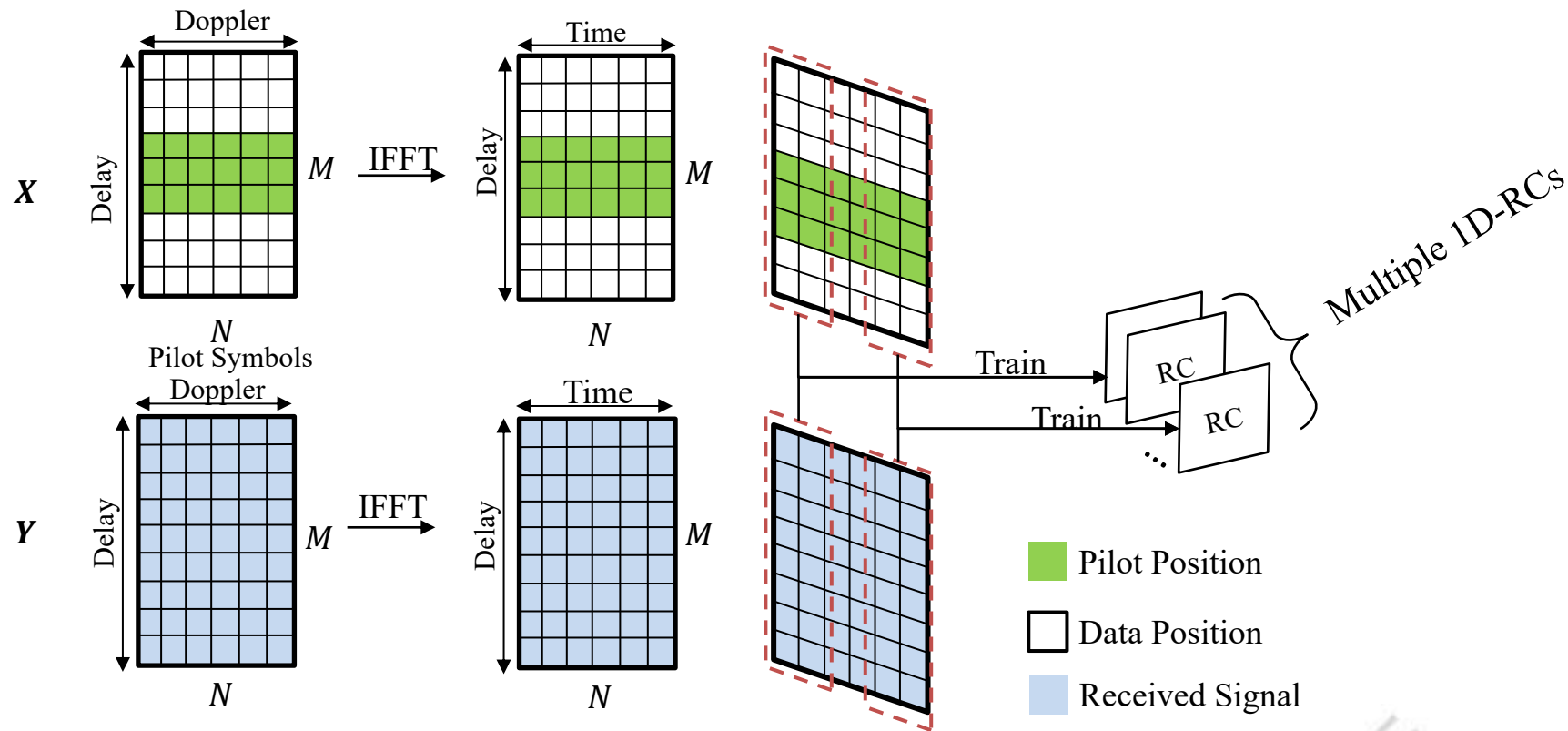
Deep Dive on Existing Online Learning Approach

- One-dimensional reservoir computing (1D-RC) approach [2]



Limitation of Existing Online Learning Approach

- Limitation of 1D-RC
 - Complicated parameter configuration of multiple 1D-RCs
 - Does not take advantage of the delay-Doppler channel representation



Introduced Two-dimensional Reservoir Computing (2D-RC)

- Two-dimensional reservoir computing (2D-RC) for OTFS symbol detection
 - Addressing the limitation
 - Operate in the delay-Doppler domain with only a **single** neural network
 - Incorporate the delay-Doppler **2D** channel interaction into the design
 - Online learning properties of 2D-RC
 - Learned with the limited OTA training pilots within the 5G slot
 - Dynamically updated on a 5G slot basis

Main Idea of 2D-RC Design

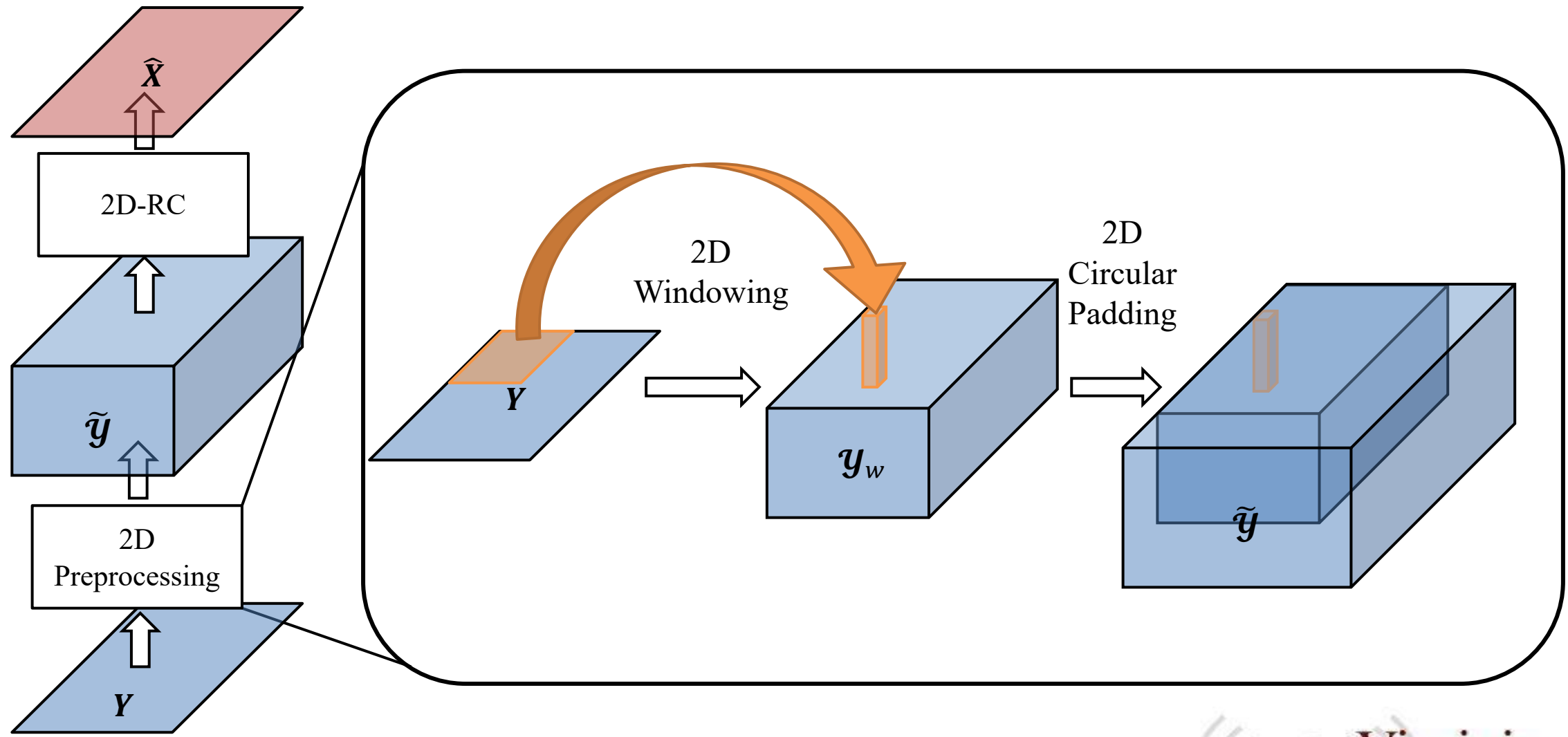
- Input-Output Relationship in the OTFS system with **rectangular** pulse shaping

$$Y[l, k] = \sum_{l'=0}^{M-1} \sum_{k'=0}^{N-1} H_{l,k}[l', k'] X[[l - l']_M, [k - k']_N] + N[l, k]$$

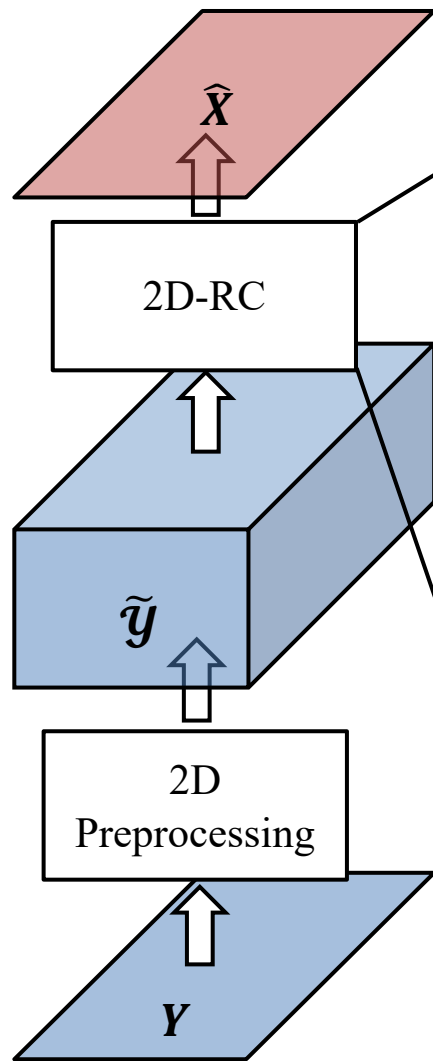
- $Y[l, k]$: (l, k) -th element of $Y \in \mathbb{C}^{M \times N}$
- $X[l, k]$: (l, k) -th element of $X \in \mathbb{C}^{M \times N}$
- $H_{l,k}[l', k']$: delay-Doppler domain effective channel (2D twisted circular convolution)
- Main Idea:
 - Delay-Doppler domain effective channel works as a 2D twisted circular convolution
 - Reservoir computing (RC) performs 1D deconvolution^[3]
 - Extend RC to have a new 2D structure to perform 2D circular deconvolution

[3] S. Jere, K. Said, L. Zheng and L. Liu, "Towards Explainable Machine Learning: The Effectiveness of Reservoir Computing in Wireless Receive Processing," *MILCOM 2023 - 2023 IEEE Military Communications Conference (MILCOM)*, Boston, MA, USA, 2023, pp. 667-672.

Design of 2D-RC: 2D Circular Padding



Design of 2D-RC: 2D Processing



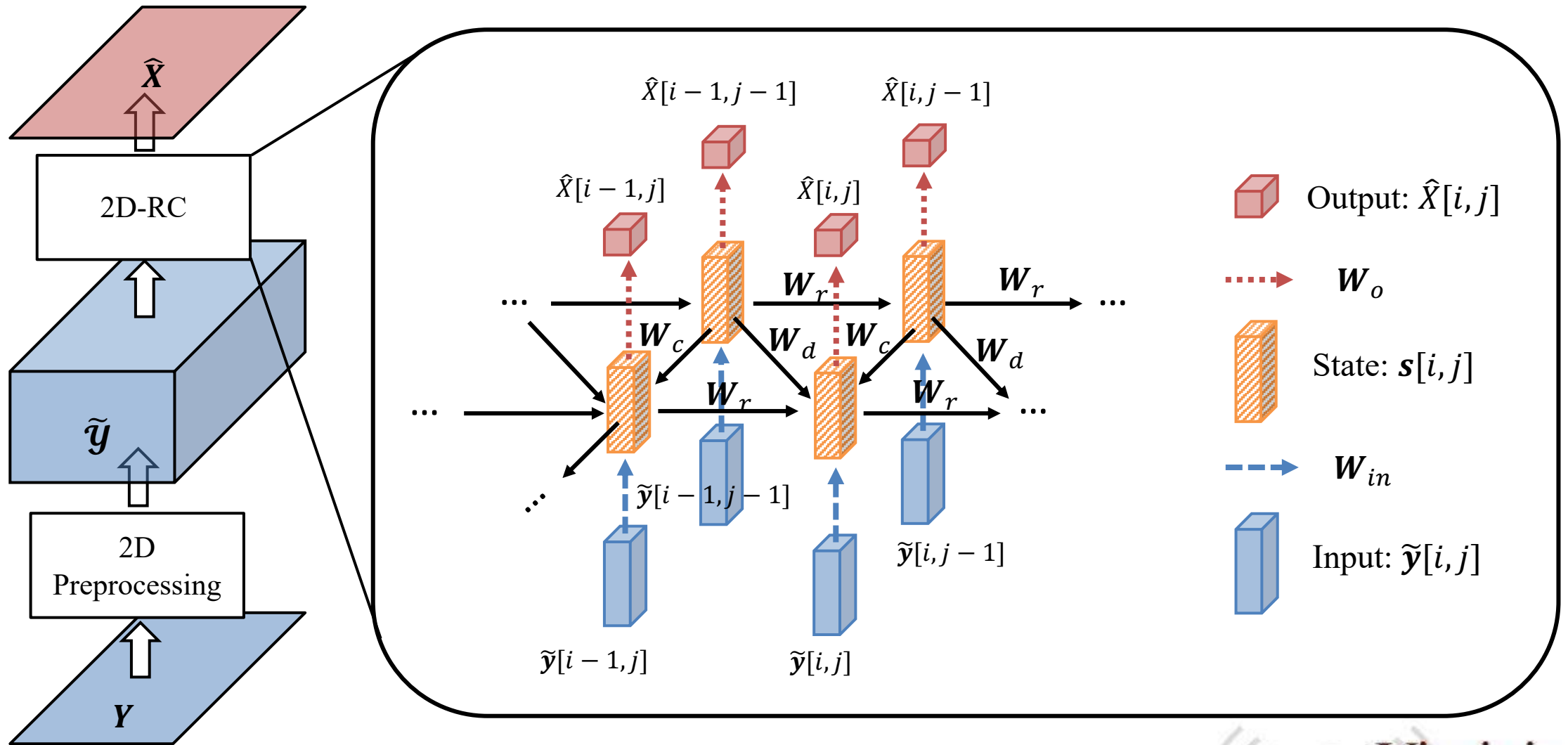
- The state transition equation and output estimation equation of 2D-RC

$$s[i, j] = f(\mathbf{W}_r s[i-1, j] + \mathbf{W}_c s[i, j-1] + \mathbf{W}_d s[i-1, j-1] + \mathbf{W}_{in} \tilde{y}[i, j])$$

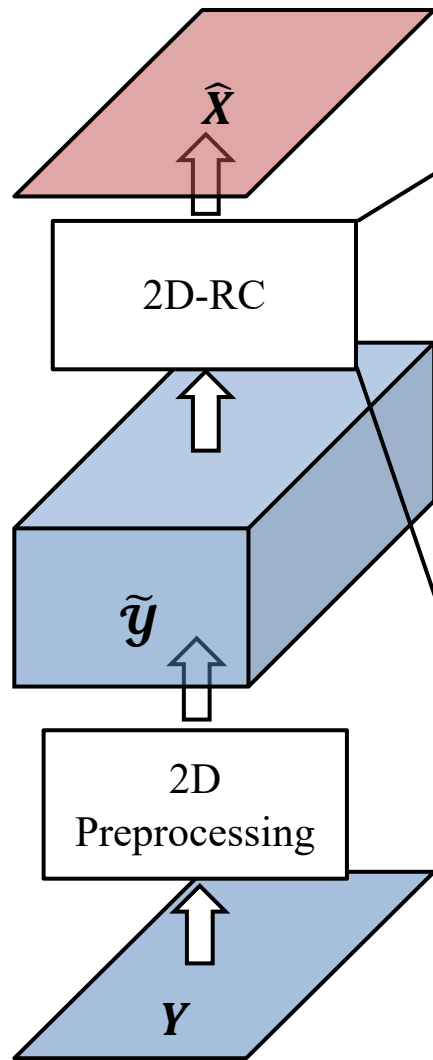
$$\tilde{s}[i, j] = \begin{bmatrix} \tilde{y}[i, j] \\ s[i, j] \end{bmatrix}$$

$$\hat{X}[i, j] = \mathbf{W}_{out} \tilde{s}[i, j]$$

Design of 2D-RC: 2D Processing

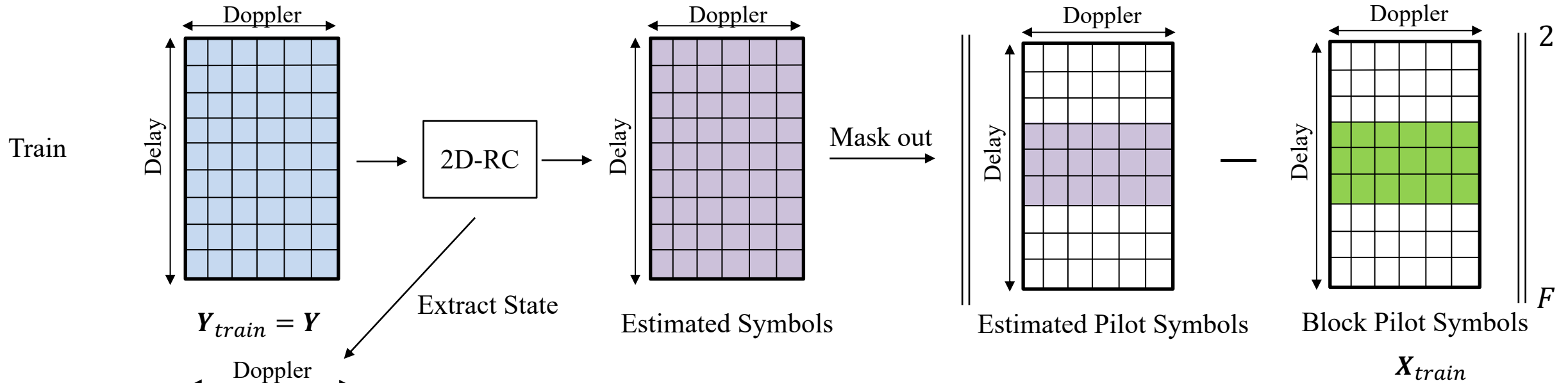


Properties and Advantages of 2D-RC

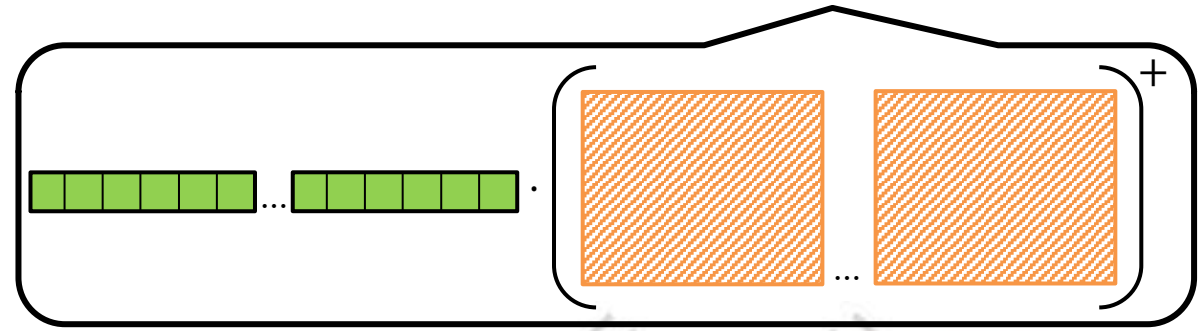


- Properties of 2D-RC
 - Fixed and randomly initialized input weights and reservoir weights
 W_{in}, W_r, W_c, W_d
 - Trainable weights:
 W_{out}
- Advantages:
 - Simple and light training procedure
 - Learn with a very limited amount of training data and short training time
 - Suitable for online learning on a 5G slot basis

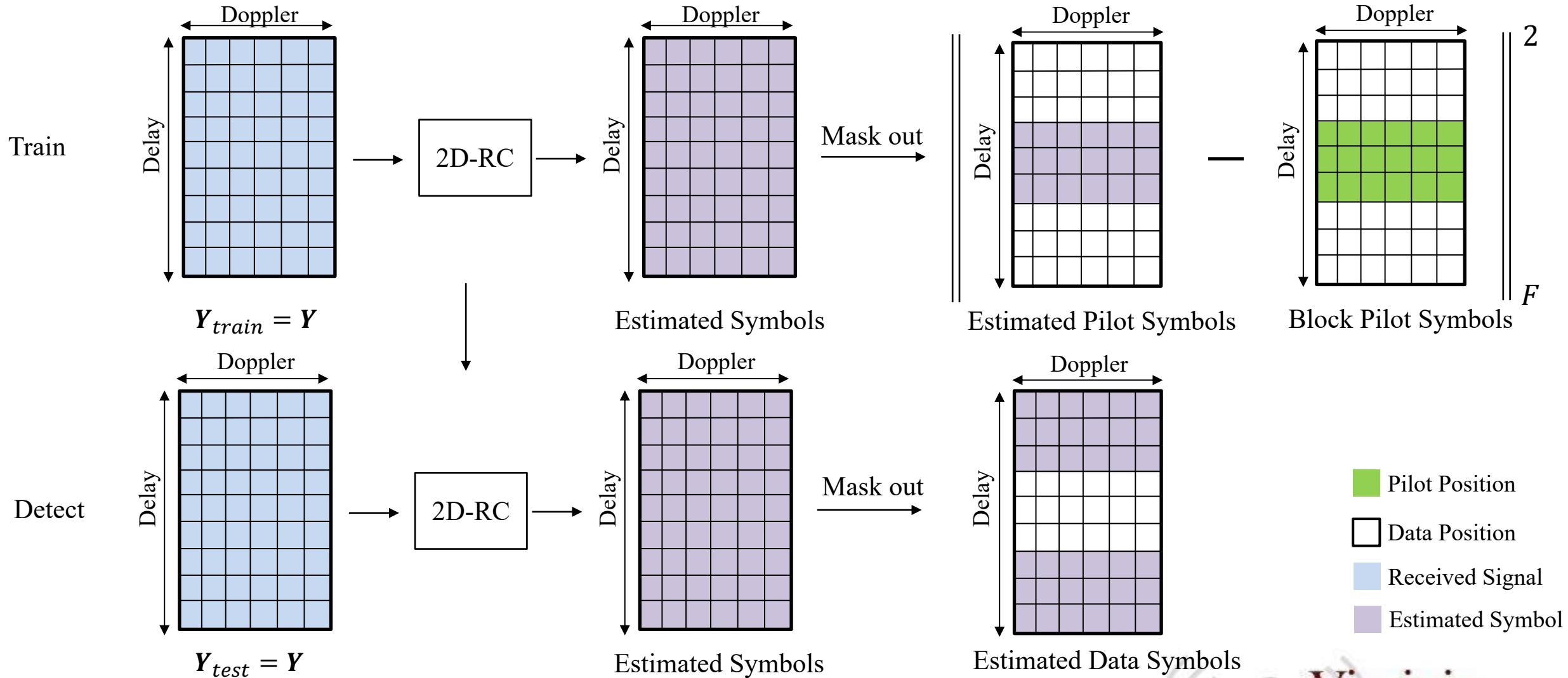
Training 2D-RC



$$\widehat{W}_{out} = \text{vec}(X_{train})^T \cdot \text{vec}_2(S_{train})^+$$

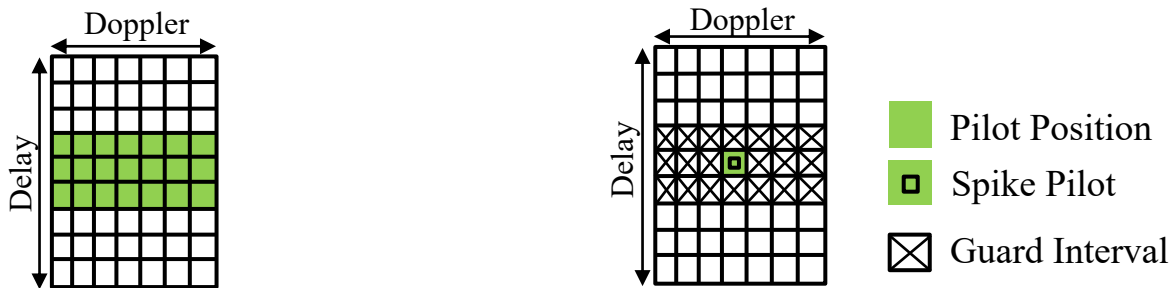


Detecting with 2D-RC



Performance Comparison

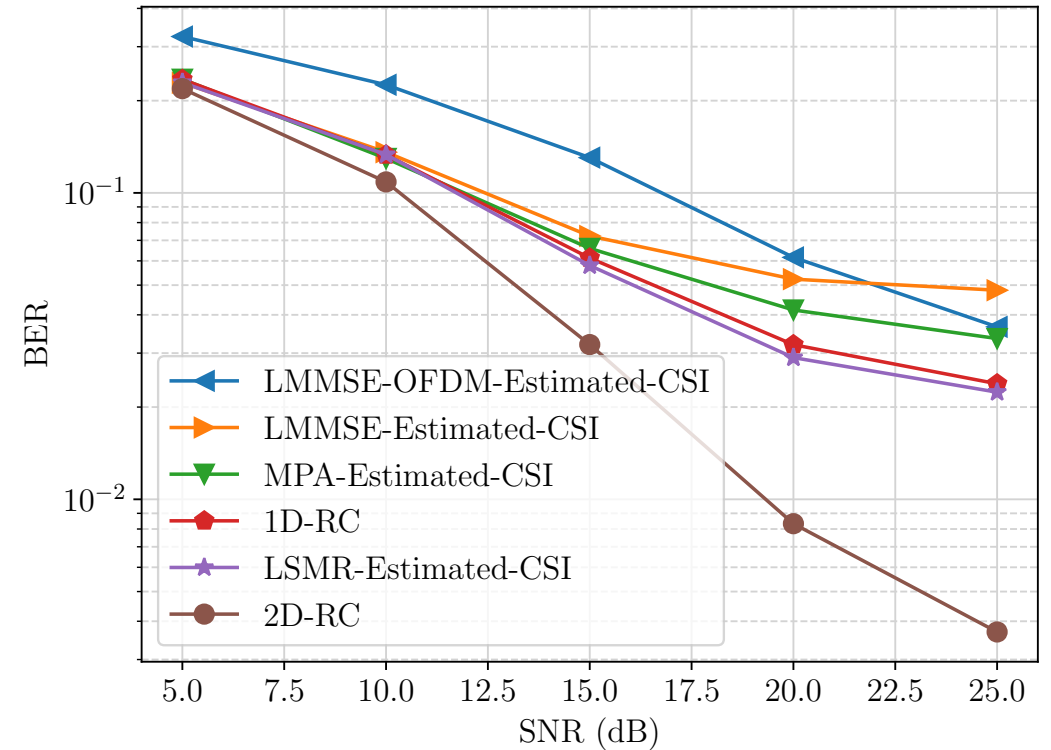
- 3GPP 5G NR clustered delay line (CDL) channel
 - User speed: 150 km/h
 - Delay profile: CDL-C
 - Carrier frequency: 4 GHz
 - Subcarrier spacing: 15 kHz
 - Number of Doppler bins (symbols): 14
 - Number of delay bins (subcarriers): 1024



Learning-based approaches: Model-based approaches:

- Block pilot pattern
- Spike pilot pattern

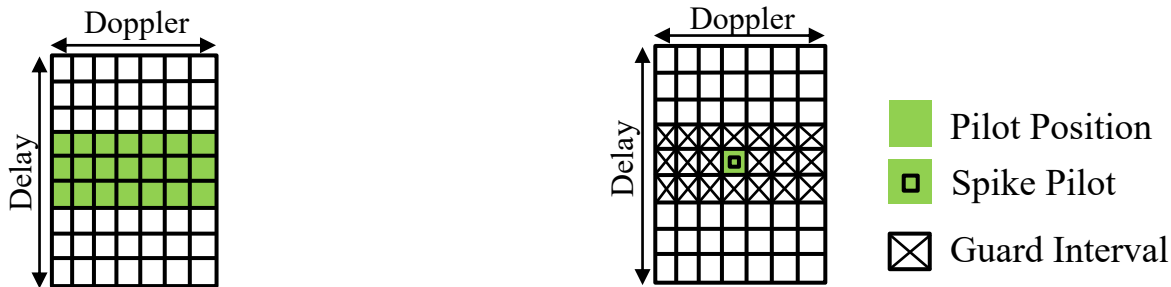
Training overhead: 4.7%



16 QAM

Performance Comparison

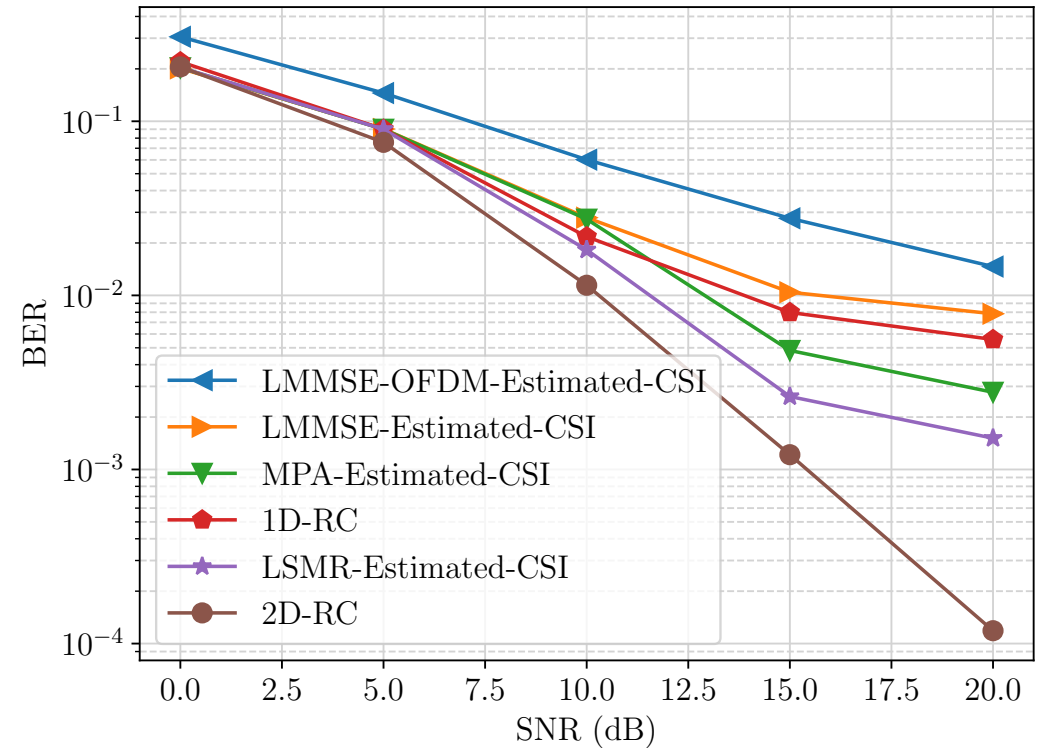
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Learning-based approaches: Model-based approaches:

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Training overhead: 4.7%



QPSK

Summary

- Introduced 2D-RC approach for OTFS symbol detection
 - Learned with the limited OTA training pilots within the 5G slot
 - Dynamically updated on a 5G slot basis
- Achieve these online properties by
 - Incorporating the delay-Doppler domain 2D channel interaction into the design
 - Extending RC to have a new 2D structure to perform 2D circular deconvolution

Thank You!



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