

Zak-OTFS and LDPC Codes

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Abstract: It is possible to read off the effective DD domain channel filter from the response to a single Zak –OTFS pilot. The more reliable estimates concentrate around the pilot, and we use this to optimize LDPC code design.

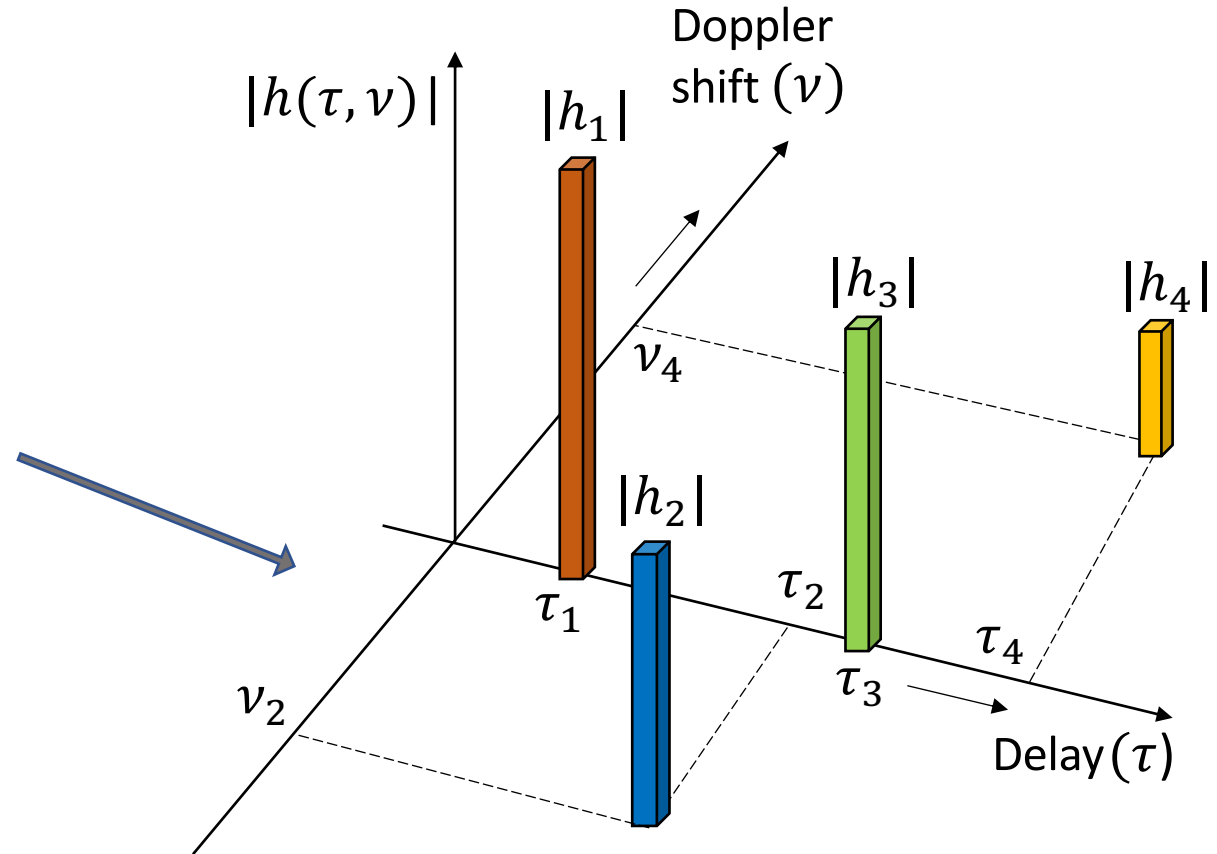
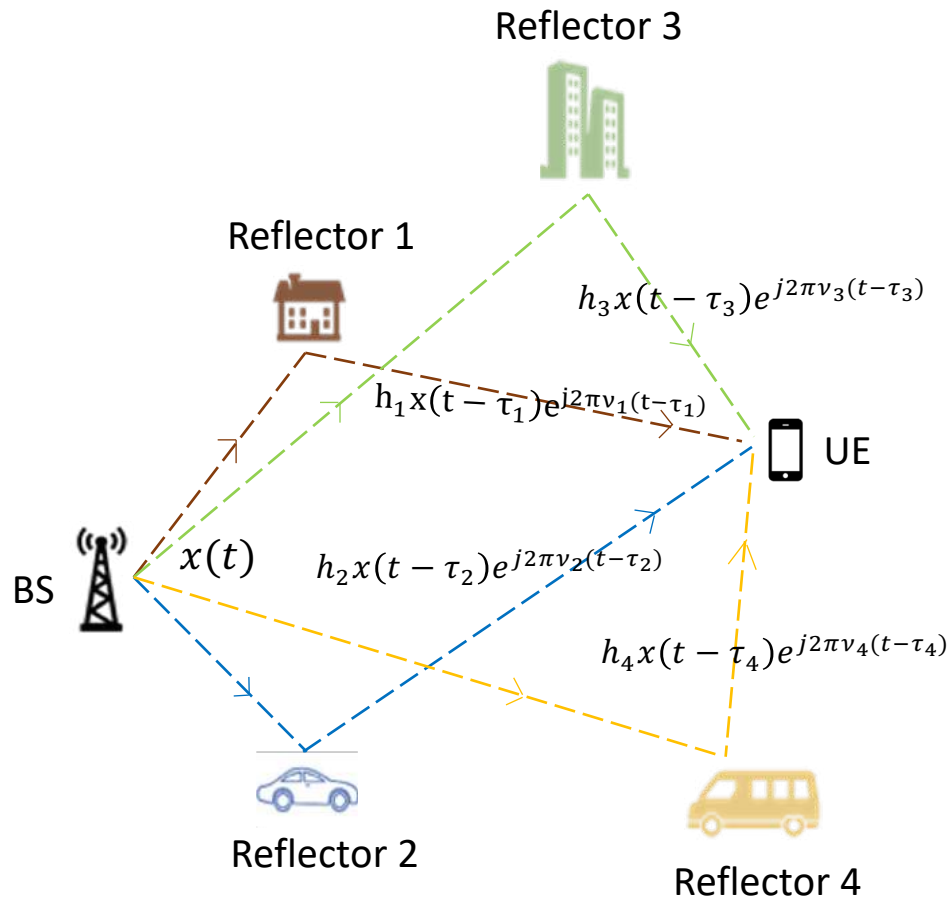
This is joint work with Beyza Dabak and Venkatesh Khammammetti

Learn More - IEEE BITS Magazine: *A Mathematical Foundation for Communications and Sensing in the Delay-Doppler Domain, Parts I and II* – in collaboration with Saif Khan Mohammed, Ronny Hadani, and Ananthanarayanan Chockalingam

Disclosure: Advisor to Cohere Technologies

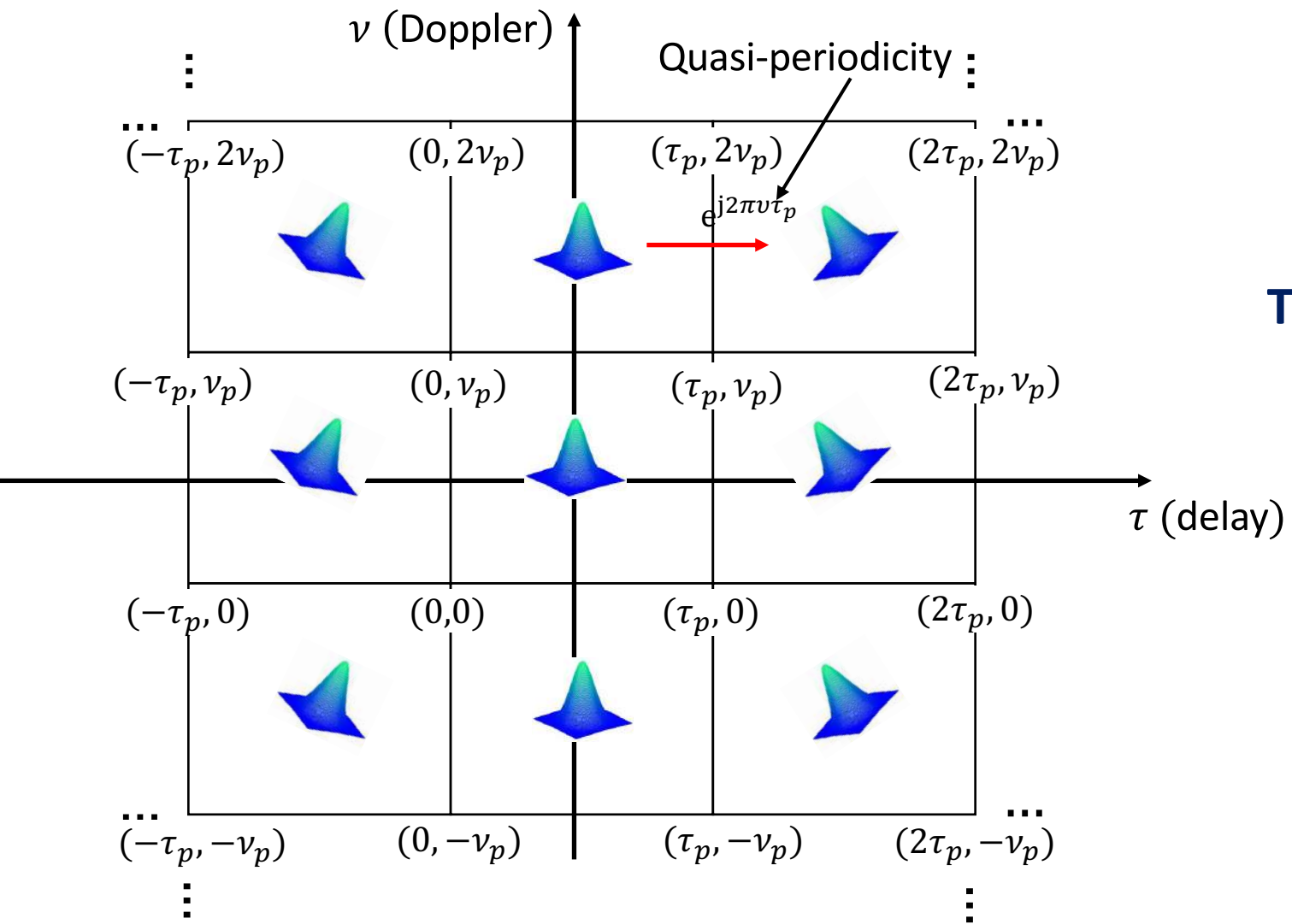
Representing Doubly Spread Channels

Taps in Delay and Doppler



Delay Spread (T_d) :-	Doppler Spread (D_s) :-
$T_d = \max_{i,j} \tau_i - \tau_j $	$D_s = \max_{i,j} \nu_i - \nu_j $

A Pulse in the Delay-Doppler Domain

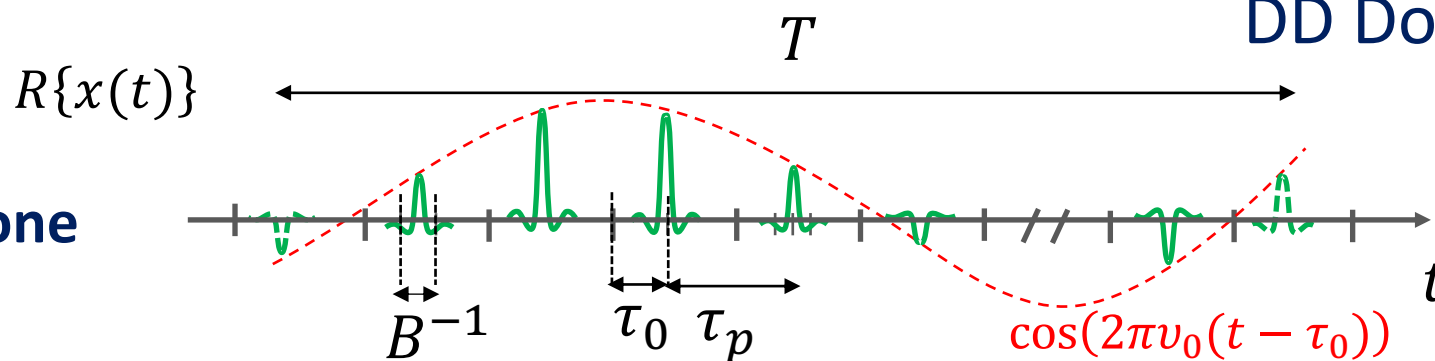


The DD realization of a TD signal is a quasi-periodic function

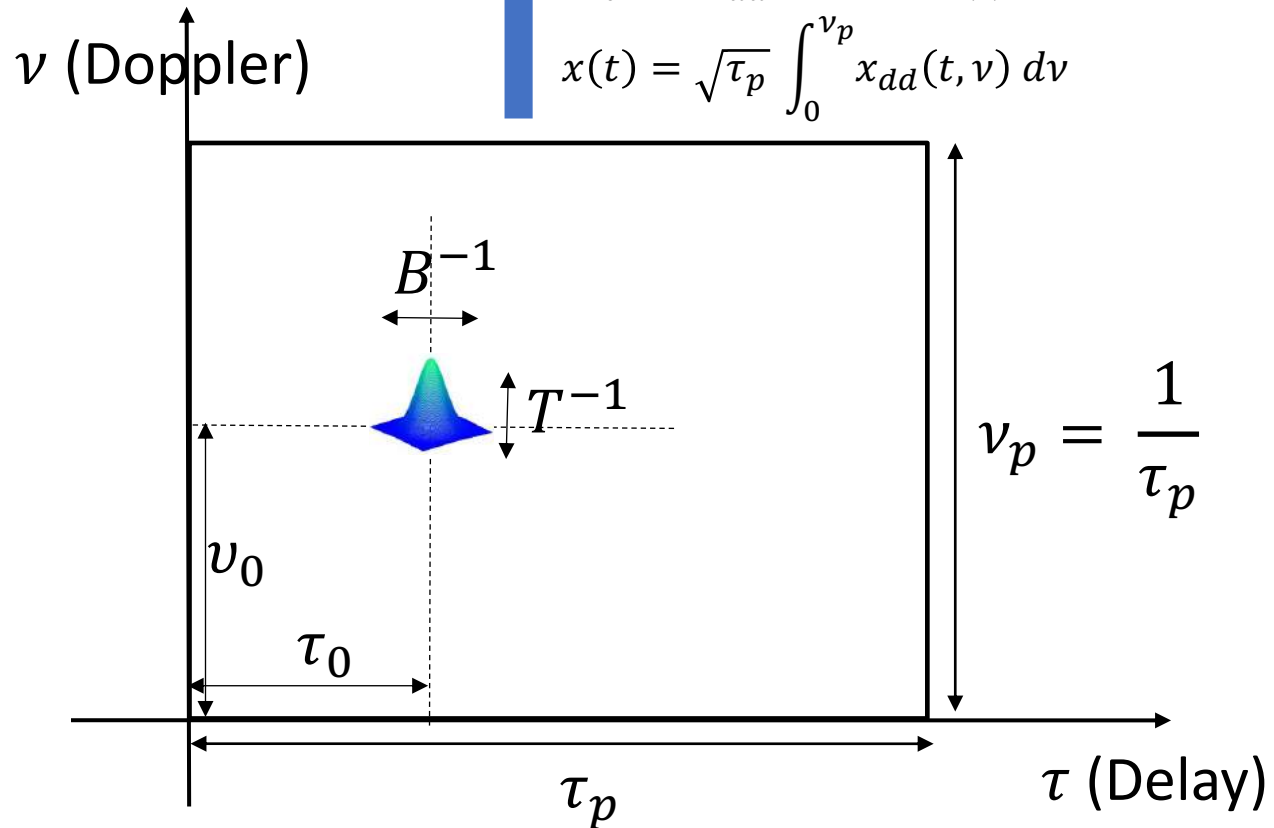
Fundamental Domain defined by the delay period τ_p and the Doppler period ν_p

TD Pulsons from a Quasi-Periodic DD Domain Pulse

TD Pulsons



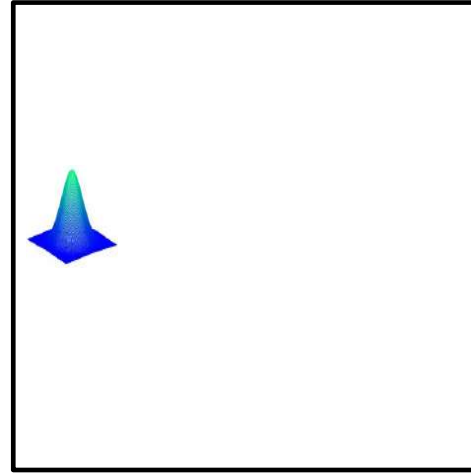
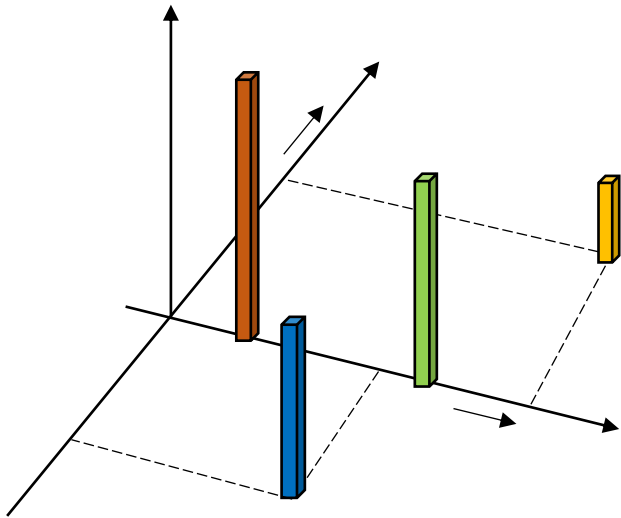
$Z_t^{-1} : x_{dd}(\tau, \nu) \rightarrow x(t)$
 $x(t) = \sqrt{\tau_p} \int_0^{\nu_p} x_{dd}(t, \nu) d\nu$



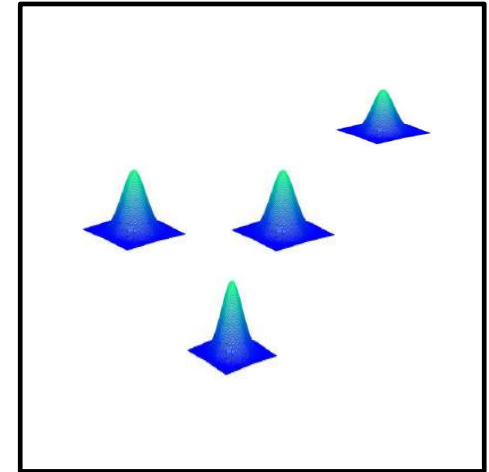
TDM is a limiting case
 FDM is a limiting case

Pulsons parametrized by τ_p interpolate between TDM and FDM

Doubly Spread Channels Acting on Pulsones



Twisted convolution:



Crystalline Regime: The delay domain period τ_p is greater than the channel path delay spread, and the Doppler domain period ν_p is greater than the path Doppler spread:

$$\tau_p > \text{delay spread} \quad \text{and} \quad \nu_p > \text{Doppler spread}$$

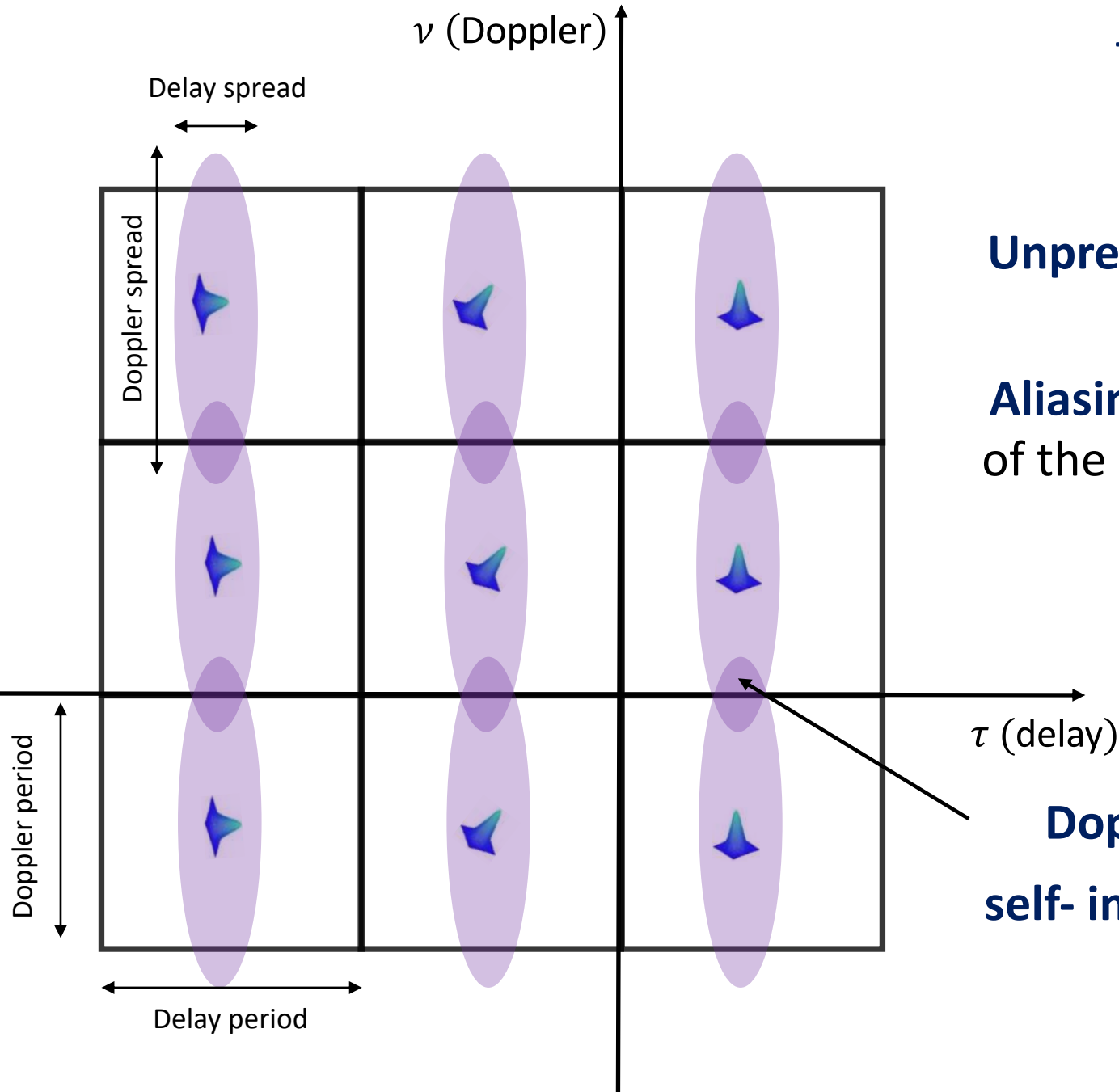
The interaction of a doubly spread channel with a TD pulsones is predictable and geometric

The Origins of Unpredictability

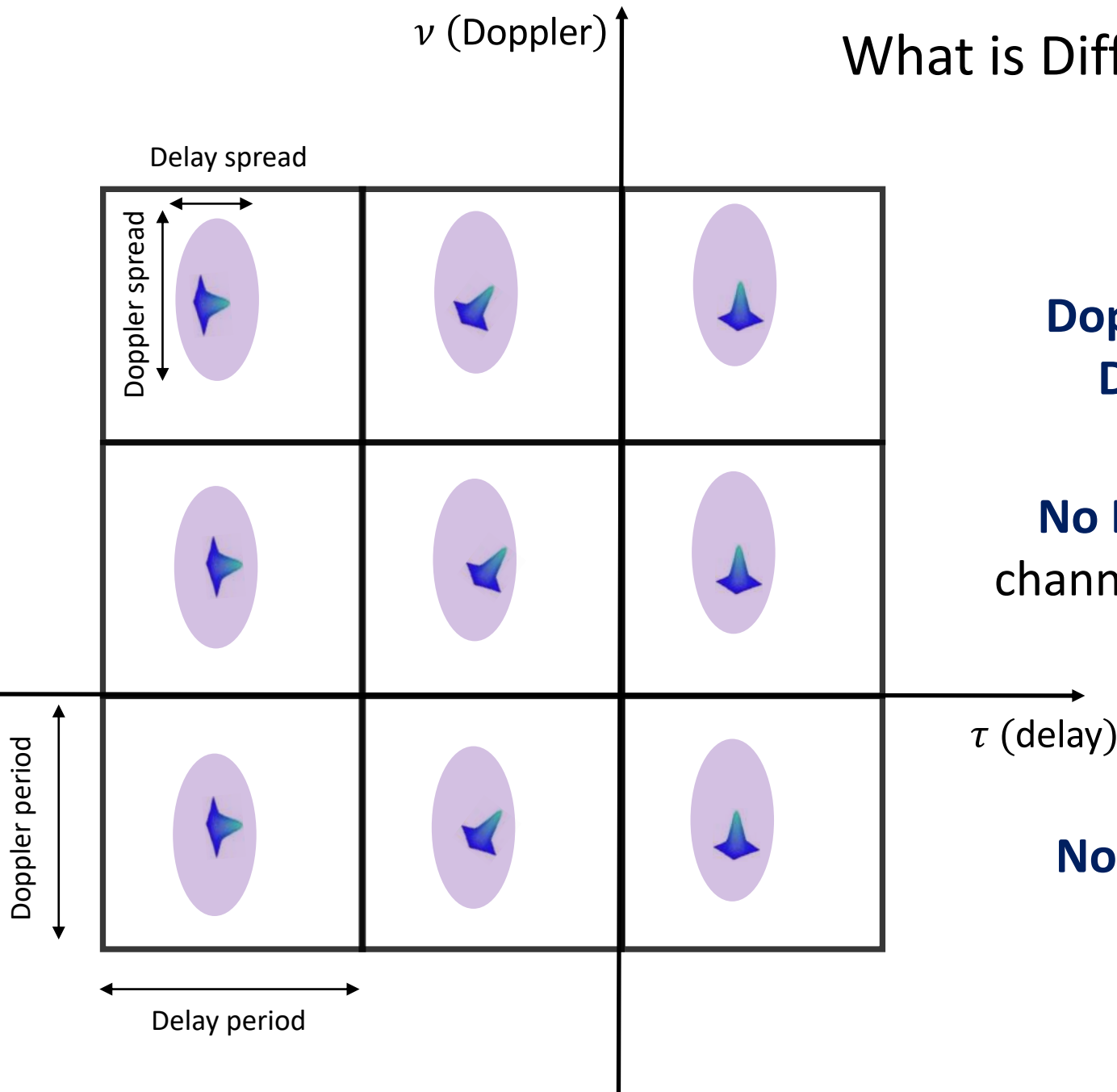
Unpredictability results from aliasing in the DD domain

Aliasing occurs when the DD spreads of the channel are bigger than the DD periods of the pulse

Doppler spread > Doppler period
self-interaction leads to unpredictability



What is Different in the Crystalline Regime?



Doppler spread < Doppler period

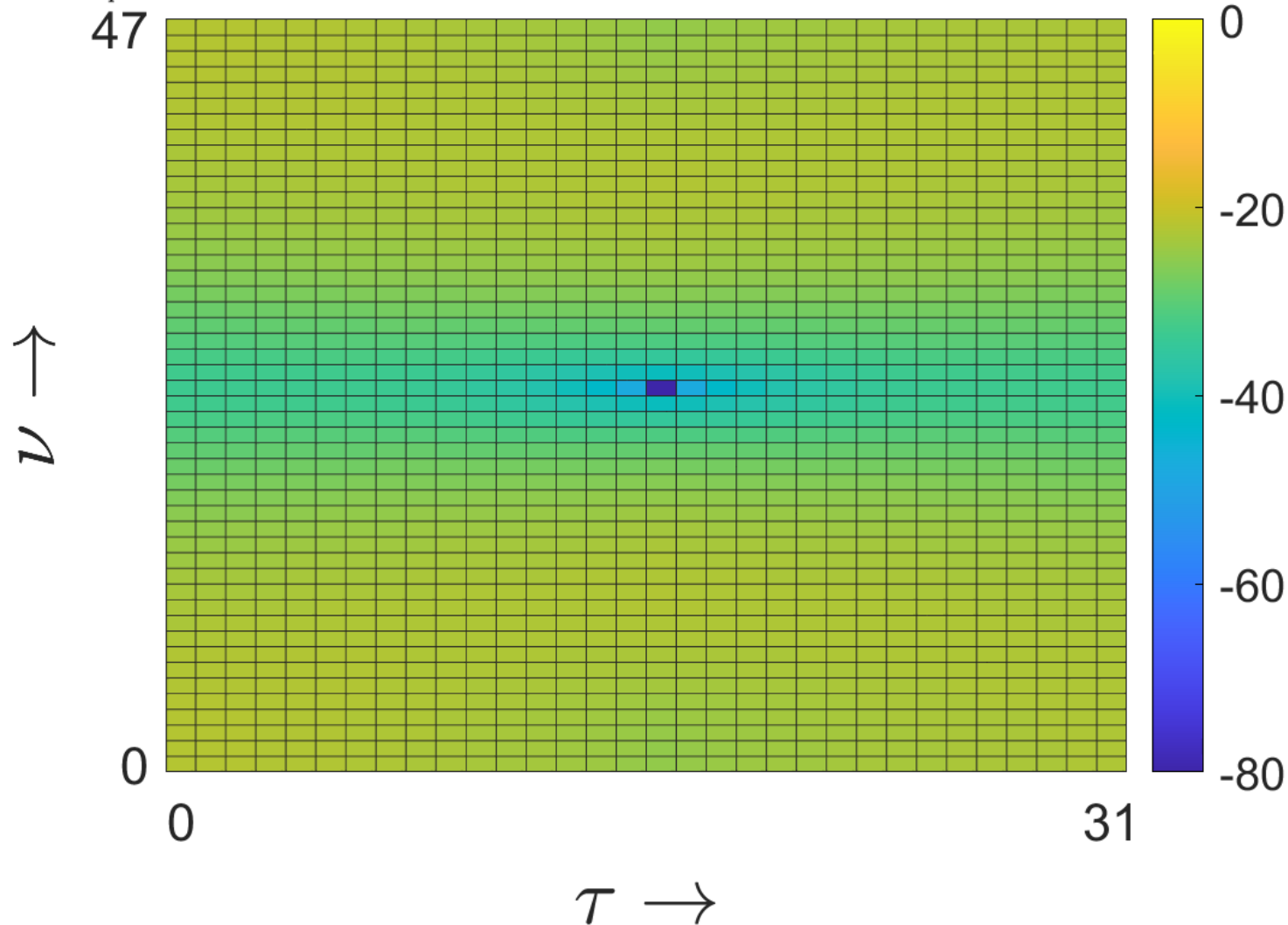
Delay spread < Delay period

No DD Aliasing - the DD spreads of the channel are smaller than the DD periods of the pulse.

No Self-Interaction means the channel response is predictable

Single Pilot Channel Estimation and RPE

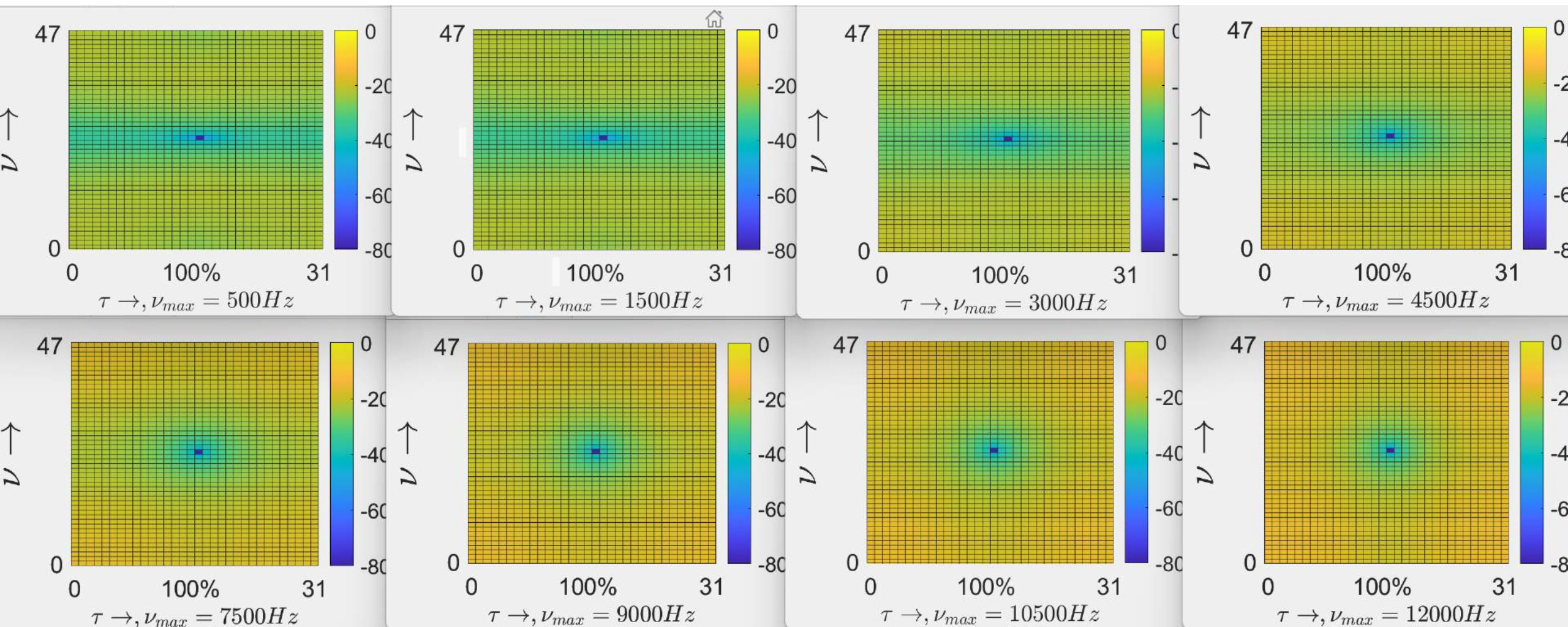
$\nu_p = 30\text{KHz}$, $B = 0.96\text{MHz}$, $T = 1.6\text{ms}$, Veh-A Ch, $\nu_{max} = 1500\text{Hz}$



Goal: Exploiting the differences in reliability with coding allocation strategies to extend the range of Doppler spreads for which reliable operation is possible

Figure: RPE with Veh-A 6 paths Channel Model

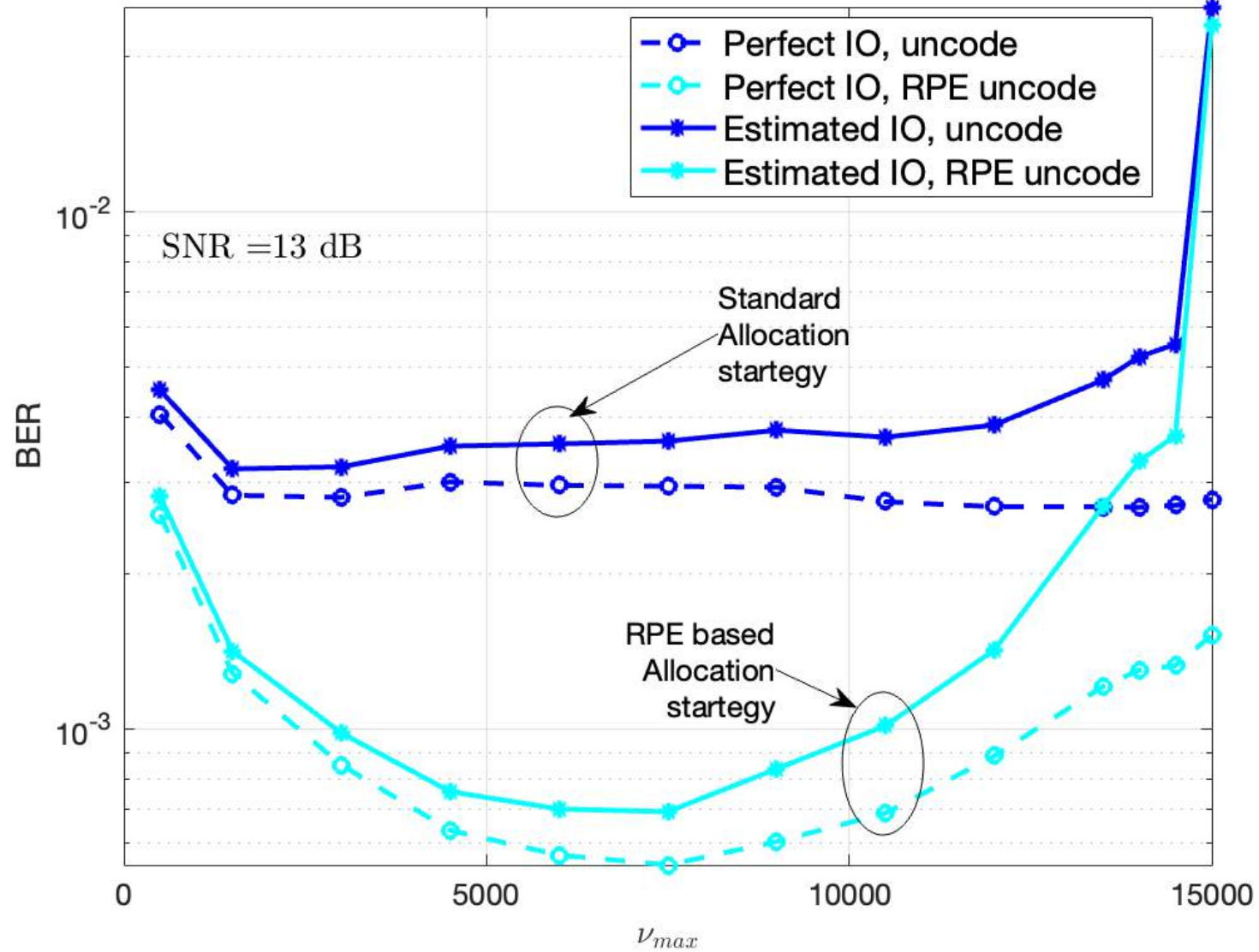
RPE with Respect to Varying Maximum Doppler Spread



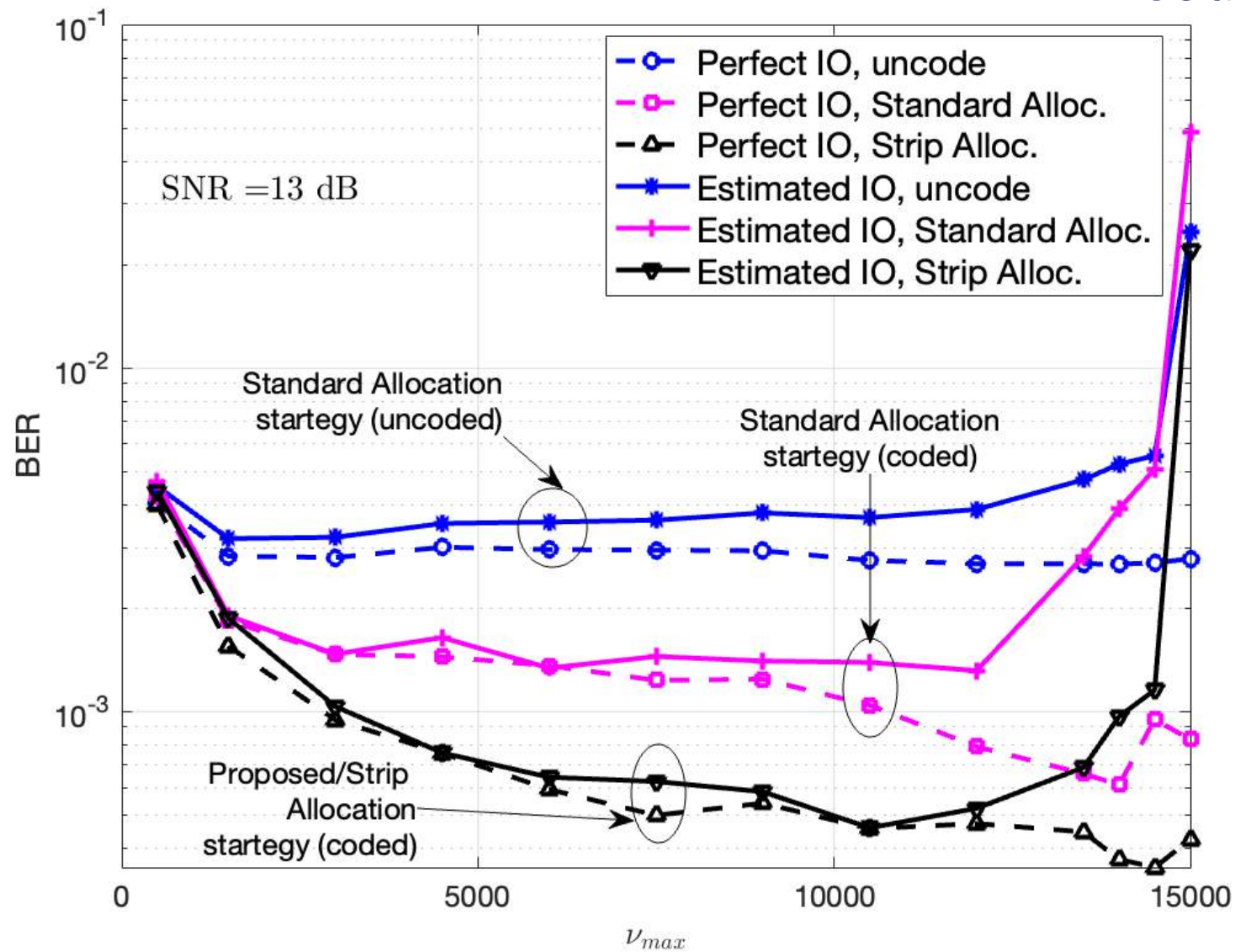
LDPC Coding

- We send a single pilot at the center of the frame and estimate the channel based on its response at the receiver.
 - The received symbols are given by, $\mathbf{y} = \mathbf{H}\mathbf{x} + \mathbf{n}$
 - MMSE equalization on the received symbols, i.e.,
$$\hat{\mathbf{x}} = (\mathbf{H}^* \mathbf{H} + \text{diag}(\sigma_i^2) \mathbf{I})^{-1} \mathbf{H}^* \mathbf{y}$$
 - For uncoded transmission, hard decoding on $\hat{\mathbf{x}}$ and generated received bits
 - For coded transmission, LLRs are input to the LDPC decoder
- Information bits are mapped to higher reliability regions with respect to RPE, while parity bits are mapped to lower reliability regions

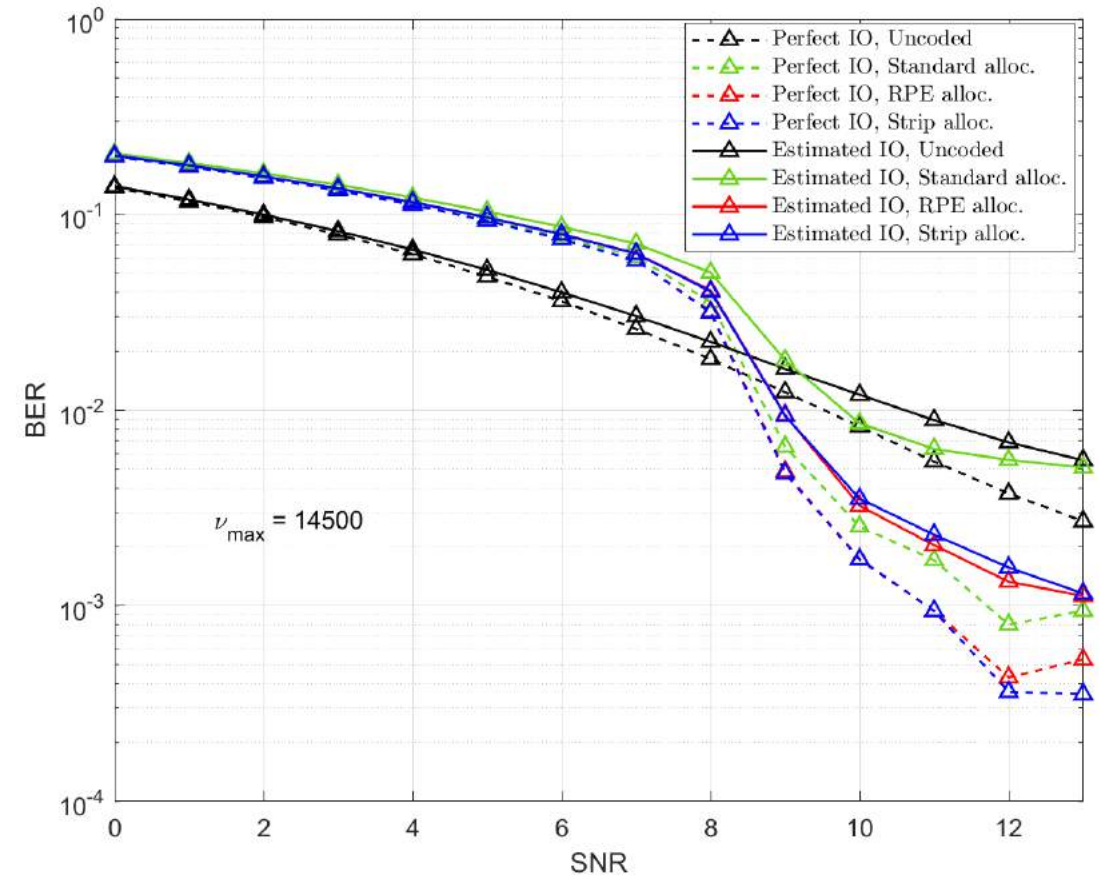
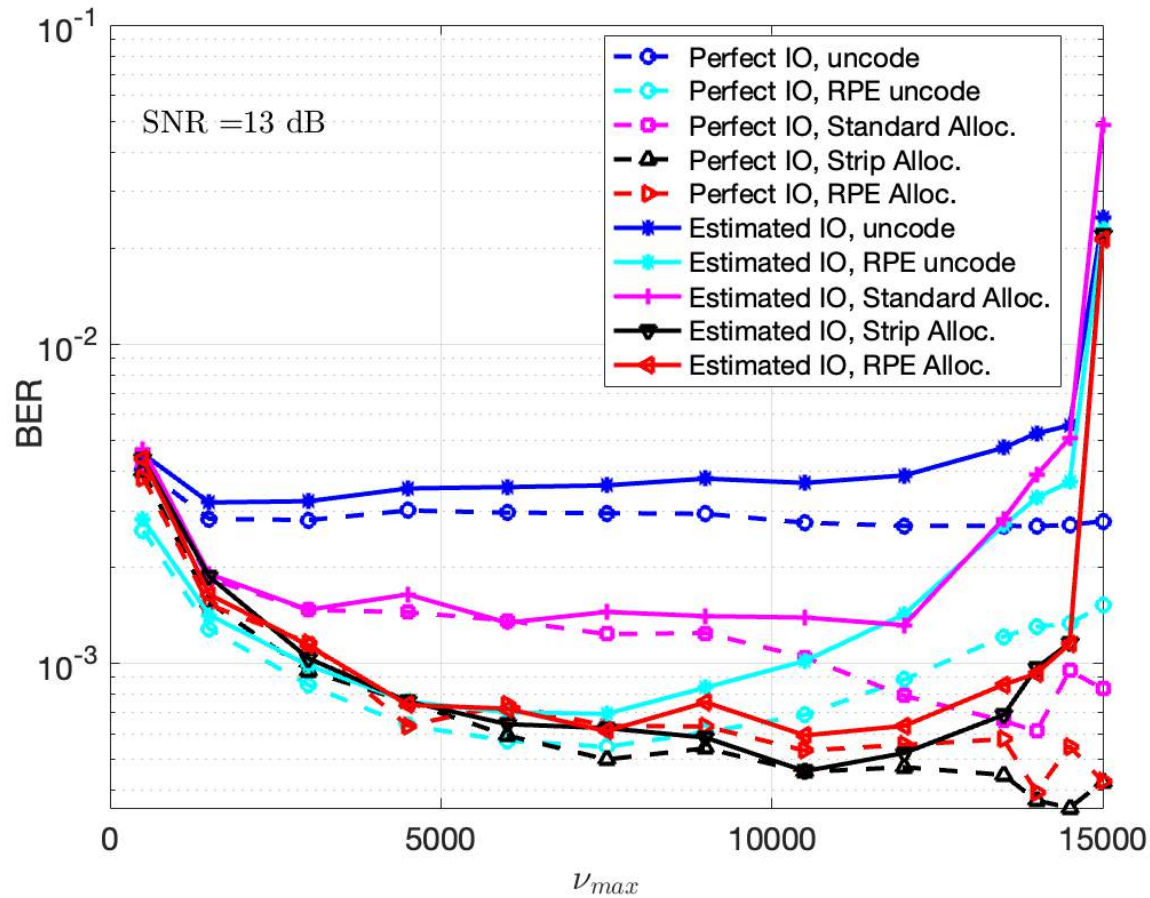
The Effect of Proposed Allocation Strategy on Uncoded Transmission



The Effect of Coding and Proposed Allocation Strategy on Coded Transmission

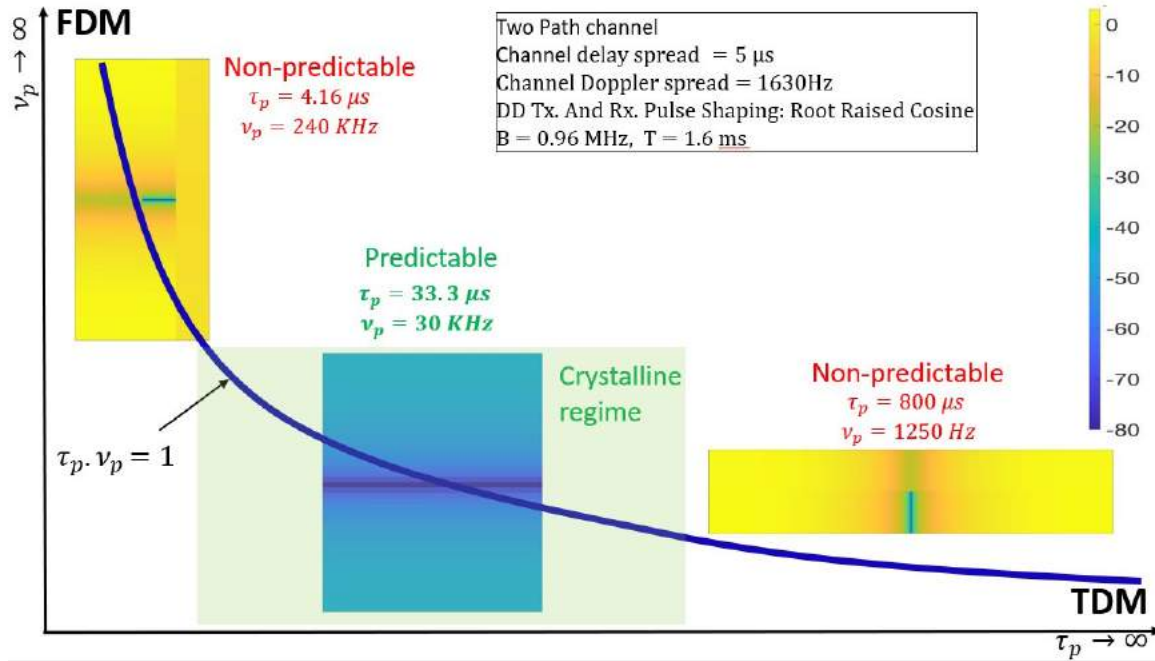


Comparison Between All Strategies for Varying Doppler Spread and Varying SNR

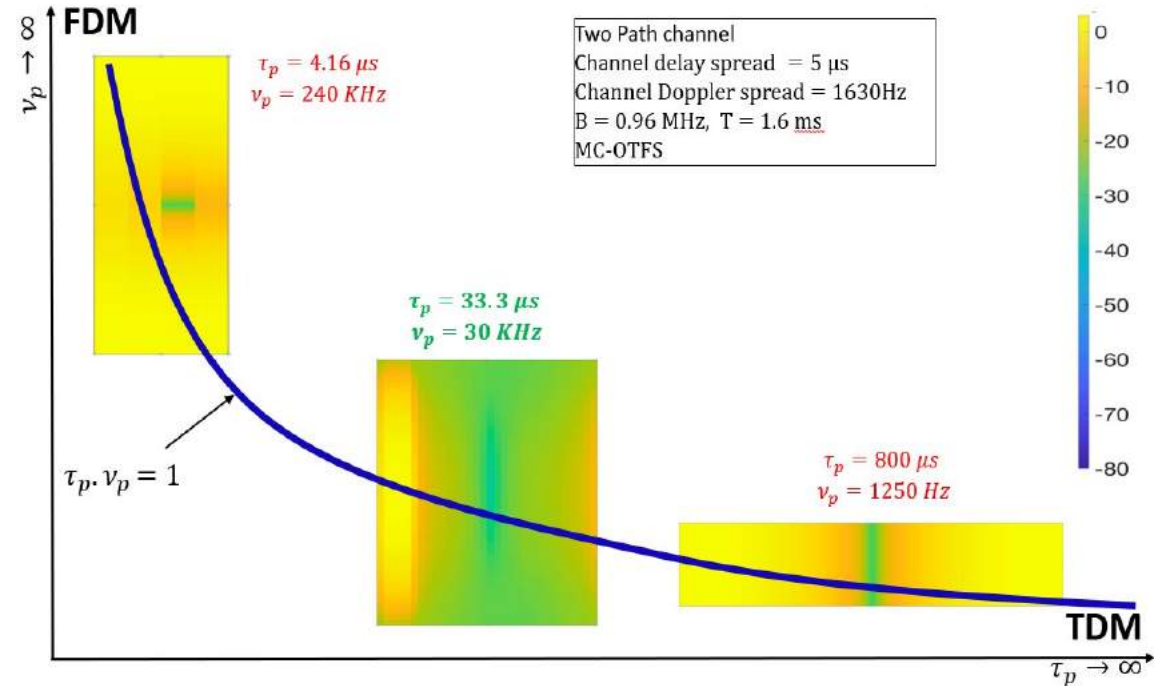


Zak-OTFS vs MC-OTFS

Predictability of the I/O Relation



Zak-OTFS



MC-OTFS

LDPC Coding in MC-OTFS versus Zak-OTFS with Different Filters

