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# Bounds on Bearing, Symbol, and Channel Estimation under Model Misspecification

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*Signals, Information, Inference, & Learning (SAIL) Group*



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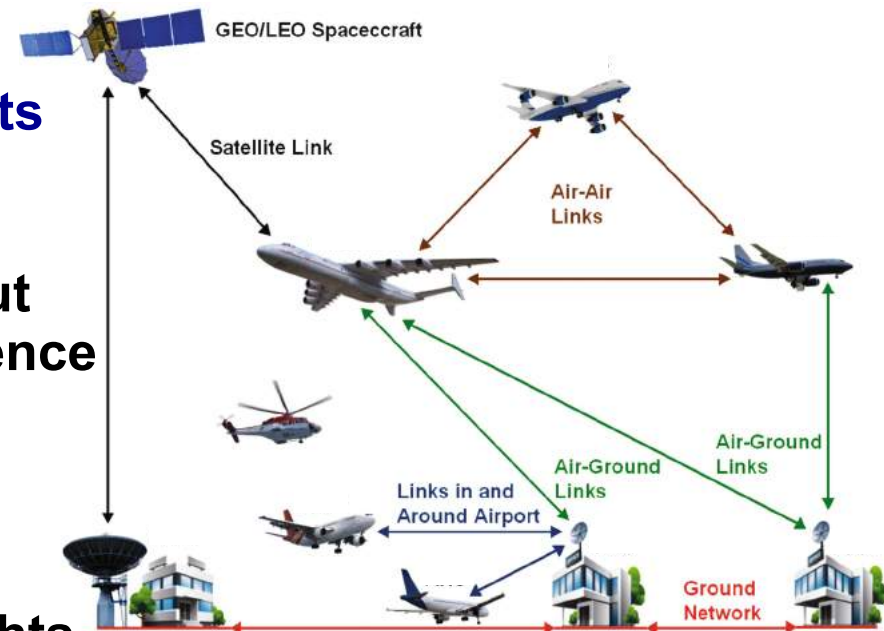


# Outline



- • **Introduction**
  - **Remarks on channels, learning, and bounds**
- Akshay's discussion
- Closing remarks

- Interest is communication link performance in **dynamic environments**
- **Deep learning** is not model-based, but requires stationary data for convergence
  - Models may be leveraged, however, to improve convergence rates
- **Models** can also provide useful insights
- **Parameter estimation** plays key role in comm. link performance
  - **Maximum-likelihood decoding** often involves symbol, channel gain, bearing, Doppler, and delay estimation, etc.



- **Cramér-Rao bound** is useful for characterizing parameter estimation performance
  - But comm. links present **some challenges**
    - **Symbols are discrete**
    - **Model is assumed known**



# Cramér-Rao Bound: Scalar Parameters



- Recall scalar **covariance inequality**:

$$1 \geq \frac{E^2\{\zeta\eta\}}{E\{\zeta^2\}E\{\eta^2\}} \quad \rightarrow \quad E\{\zeta^2\} \geq \frac{E^2\{\zeta\eta\}}{E\{\eta^2\}}$$

- Consider parameter estimate\*:  $\hat{\theta} = \hat{\theta}(\mathbf{x})$ ,  $E\{\hat{\theta}\} = \theta$ ,  $\mathbf{x} \sim p(\mathbf{x}|\theta_T)$

- Choose random variables (r.v.) as:  $\zeta = \hat{\theta} - \theta$ ,  $\eta = \frac{\partial \ln p}{\partial \theta}$  **Score Function**

- Inequality can **lower bound estimator mean squared error (MSE)**:

( Translation )<sup>2</sup>

$$E\{(\hat{\theta} - \theta)^2\} \geq \frac{E^2\left\{\left(\hat{\theta} - \theta\right) \frac{\partial \ln p}{\partial \theta}\right\}}{E\left\{\left(\frac{\partial \ln p}{\partial \theta}\right)^2\right\}} = \frac{1}{E\left\{\left(\frac{\partial \ln p}{\partial \theta}\right)^2\right\}\bigg|_{\theta=\theta_T}} = \text{CRB}(\theta_T)$$

**Cramér-Rao Bound (CRB)**

- CRB given by inverse **Fisher Information**:  $\text{FIM}(\theta) = E\left\{\left(\frac{\partial \ln p}{\partial \theta}\right)^2\right\}$
- CRB applies to all **unbiased estimators**, i.e. such that  $E\{\hat{\theta}\} = \theta$



# Cramér-Rao Bound: Vector Parameters



- Let  $\theta = [\theta_1, \theta_2, \dots, \theta_M]^T$ ,  $\hat{\theta}(\mathbf{x}) = [\hat{\theta}_1(\mathbf{x}), \hat{\theta}_2(\mathbf{x}), \dots, \hat{\theta}_M(\mathbf{x})]^T$ ,  $E\{\hat{\theta}(\mathbf{x})\} = \theta$

- **Multivariate covariance inequality:**

$$E\{\zeta\zeta^T\} \geq E\{\zeta\eta^T\}E^{-1}\{\eta\eta^T\}E\{\eta\zeta^T\}$$

- **Variable choice for  $\zeta$  and  $\eta$  lower bounds estimator MSE matrix:**

$$\zeta = \hat{\theta} - \theta, \quad \eta = \frac{\partial \ln p(\mathbf{x}|\theta)}{\partial \theta} \quad \Rightarrow \quad E\{\zeta\zeta^T\} = \text{Cov}(\hat{\theta}) = E\{(\hat{\theta} - \theta)(\hat{\theta} - \theta)^T\} \geq \text{CRB}(\theta)$$

- **Fisher information matrix (FIM) and translation matrix:**

$$\mathbf{J}(\theta) \triangleq E\left\{ \frac{\partial \ln p(\mathbf{x}|\theta)}{\partial \theta} \frac{\partial \ln p(\mathbf{x}|\theta)}{\partial \theta}^T \right\}, \quad \Xi(\theta) \triangleq E\left\{ \frac{\partial \ln p(\mathbf{x}|\theta)}{\partial \theta} (\hat{\theta} - \theta)^T \right\} = \mathbf{I}_M$$

*(Note:  $E\{\eta\eta^T\}$  is indicated by a blue checkmark under the FIM definition, and  $E\{\eta\zeta^T\}$  is indicated by a blue checkmark under the translation matrix definition.)*

- **CRB lower bound for unbiased estimators given by:**

$$E\{(\hat{\theta} - \theta)(\hat{\theta} - \theta)^T\} \geq \mathbf{J}^{-1}(\theta) \quad \Rightarrow \quad E\{[\hat{\theta}_i(\mathbf{x}) - \theta_i]^2\} \geq [\mathbf{J}^{-1}(\theta)]_{i,i}$$



# Cramér-Rao Bound: FIM Slepian Formula



- Let parameters be given by  $\theta = [\theta_1, \theta_2, \dots, \theta_M]^T$
- Assume data is **complex Gaussian**, i.e.  $\tilde{\mathbf{x}} \sim \mathcal{CN}(\mu(\theta), \tilde{\mathbf{R}}) = p(\tilde{\mathbf{x}}|\theta)$ 
  - Only mean is parameterized by  $\theta$
- **Slepian formula** for FIM, denoted  $\mathbf{J}(\theta)$ , is given by

$$\mathbf{J}(\theta) = \frac{\partial \mu^*}{\partial \theta^*} \tilde{\mathbf{R}}^{-1} \left( \frac{\partial \mu}{\partial \theta} \right)^T + \frac{\partial \mu}{\partial \theta^*} \left( \tilde{\mathbf{R}}^{-1} \right)^* \left( \frac{\partial \mu^*}{\partial \theta} \right)^T$$

- Cramér-Rao bound:

$$\mathbb{E} \left[ \left( \hat{\theta} - \theta \right) \left( \hat{\theta} - \theta \right)^H \right] \geq \mathbf{J}^{-1}(\theta)$$



# Constrained Cramér-Rao Bound



1. Given  $m$  constraints on  $\theta$ :  $\mathbf{f}(\theta) = [f_1(\theta), \dots, f_m(\theta)]^T = \mathbf{0}_{m \times 1}$

2. Gradient matrix  $\mathbf{F}(\theta)$ :  $\mathbf{F}(\theta) = \left[ \frac{\partial \mathbf{f}(\theta)}{\partial \theta^*} \right]^T$

3. There exists a unitary matrix  $\mathbf{U}_{M \times (M-m)}$  such that

$$\mathbf{F}(\theta)\mathbf{U} = \mathbf{0}_{m \times (M-m)}$$

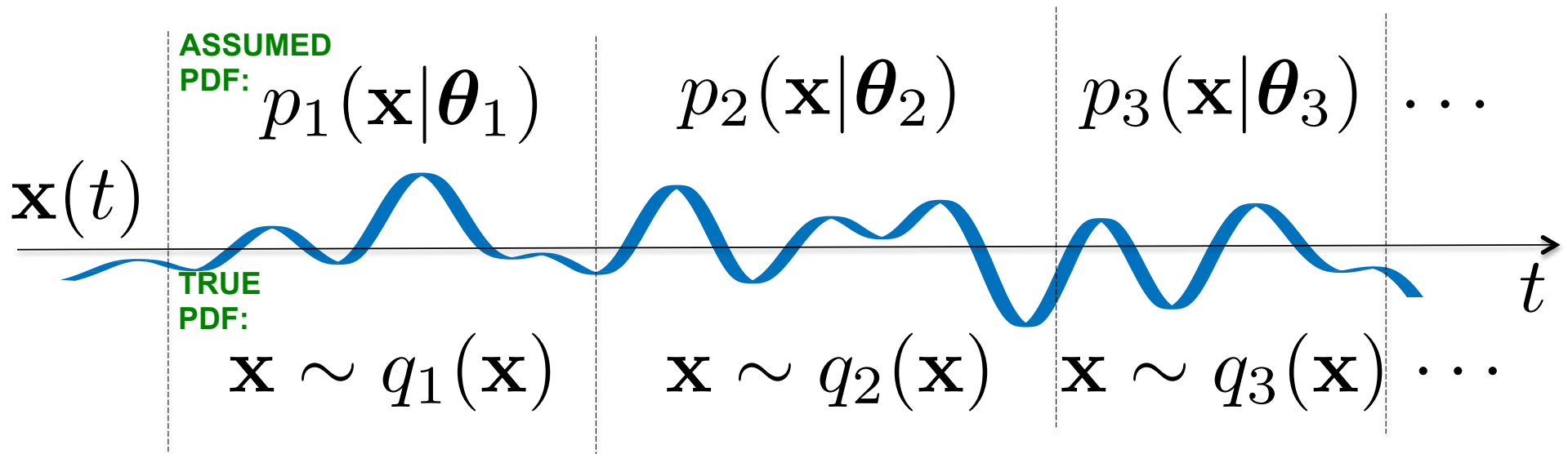
## 4. CCRB

$$\mathbb{E} \left[ \left( \hat{\theta} - \theta \right) \left( \hat{\theta} - \theta \right)^H \right] \geq \mathbf{U} \left( \mathbf{U}^H \mathbf{J}(\theta) \mathbf{U} \right)^{-1} \mathbf{U}^H$$

Will use CCRB to address any **discrete parameters**

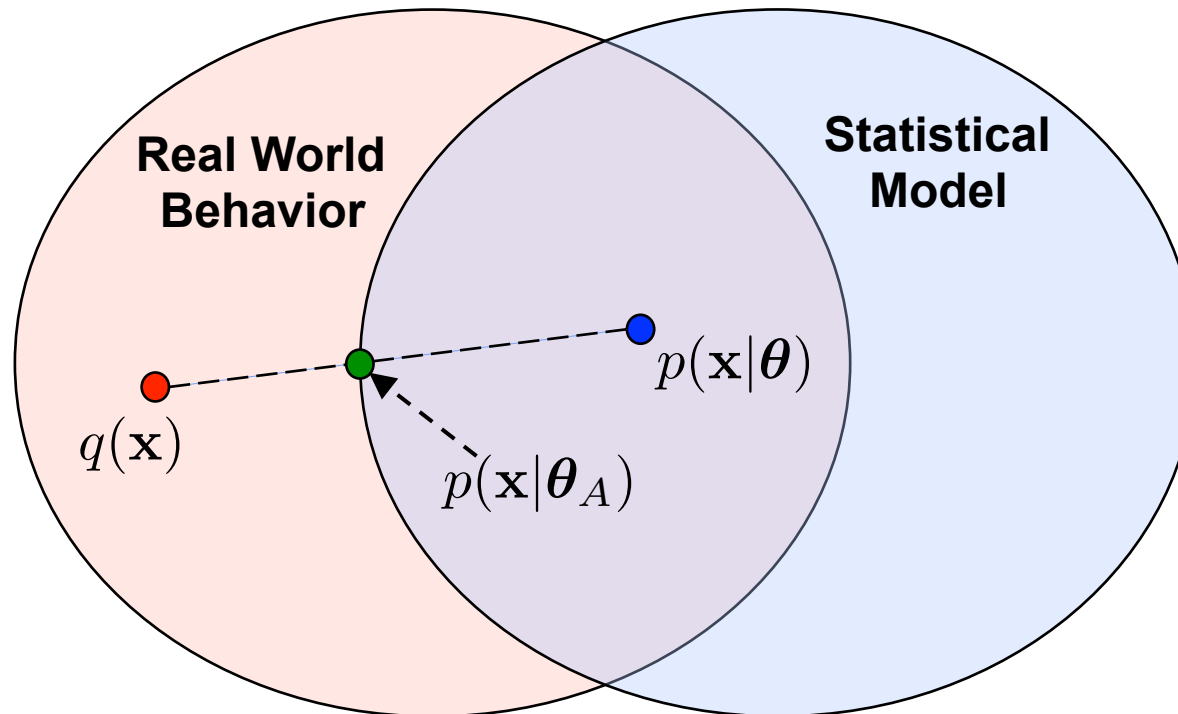


# Remarks on Dynamic Comm. Channels



- Possible initial framework for modeling dynamic channels
- Simulated data can feed deep learning algorithms
- Models can provide metrics by which to measure performance
- Models may help resolve/improve deep learning performance





- **Consider  $x \sim q(x) \neq p(x|\theta)$  for all  $\theta$  is allowed**
  - **Distance between  $q(x)$  and  $p(x|\theta)$  may be bounded away from zero**
- **What can be said about limits of parameter estimation?**
  - **How well can we expect to do?**



# Misspecified Cramér-Rao Bound (MCRB)



- Consider complex data  $\tilde{\mathbf{x}}$  with distributions:

**True:**  $\tilde{\mathbf{x}} \sim q(\tilde{\mathbf{x}}) = \mathcal{CN}(\mathbf{d}, \tilde{\mathbf{R}})$ , **Assumed:**  $\tilde{\mathbf{x}} \sim p(\tilde{\mathbf{x}}|\boldsymbol{\theta}) = \mathcal{CN}(\boldsymbol{\mu}(\boldsymbol{\theta}), \tilde{\mathbf{R}})$

– *Mean is parameterized* and  $\boldsymbol{\mu}(\boldsymbol{\theta}) \neq \mathbf{d}$  for all  $\boldsymbol{\theta}$  is allowed\*

- Define  $\delta\boldsymbol{\mu}(\boldsymbol{\theta}) \triangleq \mathbf{d} - \boldsymbol{\mu}(\boldsymbol{\theta})$ , and matrices:

$$\mathbf{J}(\boldsymbol{\theta}) \triangleq \left( \frac{\partial \boldsymbol{\mu}^*(\boldsymbol{\theta})}{\partial \boldsymbol{\theta}^*} \right) \tilde{\mathbf{R}}^{-1} \left( \frac{\partial \boldsymbol{\mu}(\boldsymbol{\theta})}{\partial \boldsymbol{\theta}} \right)^T + \left( \frac{\partial \boldsymbol{\mu}(\boldsymbol{\theta})}{\partial \boldsymbol{\theta}^*} \right) (\tilde{\mathbf{R}}^{-1})^* \left( \frac{\partial \boldsymbol{\mu}^*(\boldsymbol{\theta})}{\partial \boldsymbol{\theta}} \right)^T$$

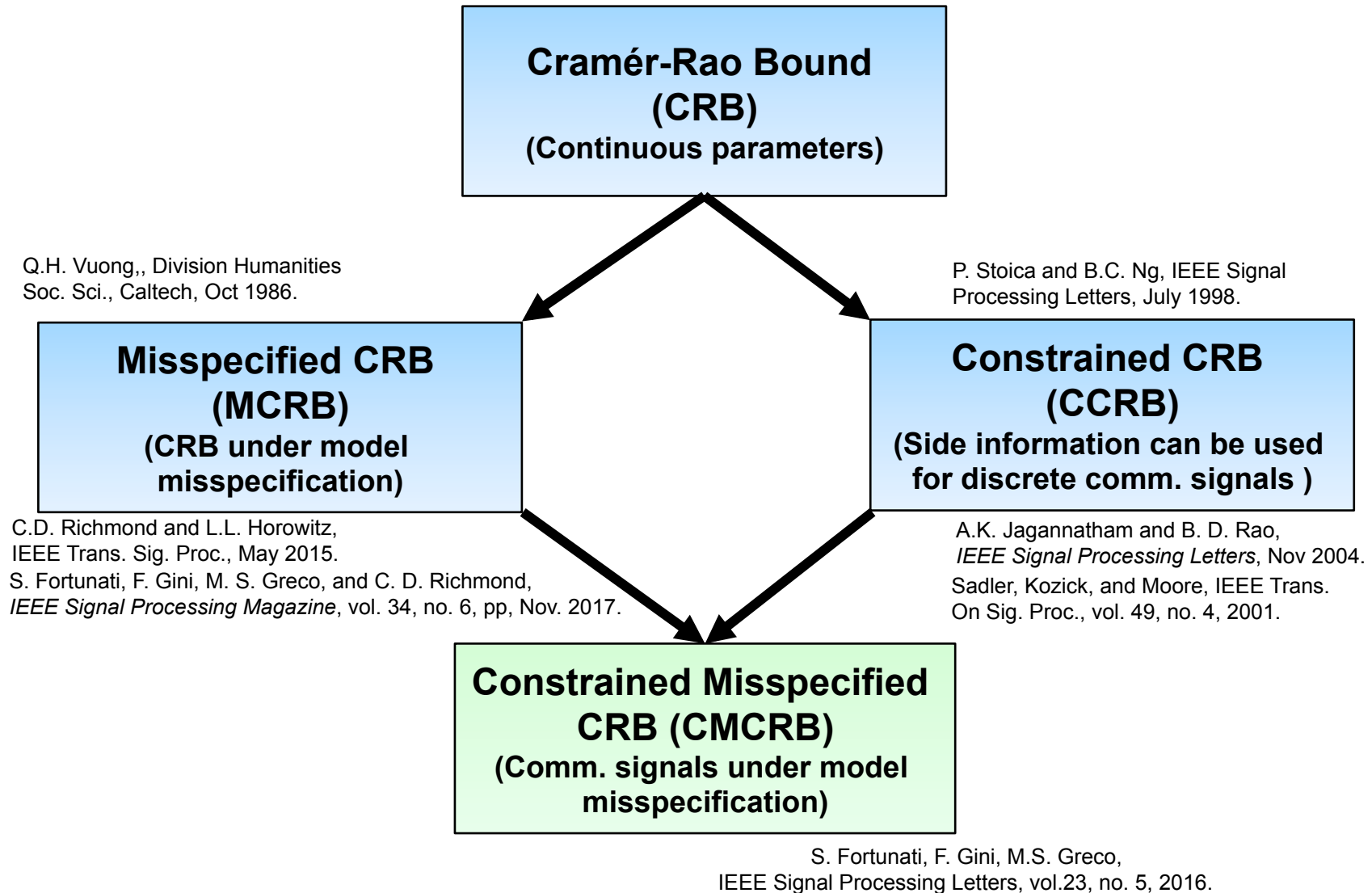
$$\begin{aligned} [\mathbf{C}(\boldsymbol{\theta})]_{i,k} \triangleq & - \left[ \frac{\partial \boldsymbol{\mu}^*(\boldsymbol{\theta})}{\partial \theta_i^*} \right]^T \tilde{\mathbf{R}}^{-1} \frac{\partial \boldsymbol{\mu}(\boldsymbol{\theta})}{\partial \theta_k} - \left[ \frac{\partial \boldsymbol{\mu}^*(\boldsymbol{\theta})}{\partial \theta_k} \right]^T \tilde{\mathbf{R}}^{-1} \frac{\partial \boldsymbol{\mu}(\boldsymbol{\theta})}{\partial \theta_i^*} \\ & + \left[ \frac{\partial^2 \boldsymbol{\mu}^*(\boldsymbol{\theta})}{\partial \theta_i^* \partial \theta_k} \right]^T \tilde{\mathbf{R}}^{-1} \delta\boldsymbol{\mu}(\boldsymbol{\theta}) + \delta\boldsymbol{\mu}^H(\boldsymbol{\theta}) \tilde{\mathbf{R}}^{-1} \frac{\partial^2 \boldsymbol{\mu}(\boldsymbol{\theta})}{\partial \theta_i^* \partial \theta_k} \end{aligned}$$

- Let  $\boldsymbol{\theta}_A \triangleq \arg \min_{\boldsymbol{\theta}} D(q_{\tilde{\mathbf{x}}} || p_{\tilde{\mathbf{x}}|\boldsymbol{\theta}})$  and  $E_q\{\hat{\boldsymbol{\theta}}\} = \boldsymbol{\theta}_A$ . The MCRB is given by\*\*:

$$E_q \left\{ (\hat{\boldsymbol{\theta}} - \boldsymbol{\theta}_A)(\hat{\boldsymbol{\theta}} - \boldsymbol{\theta}_A)^H \right\} \geq \mathbf{C}^{-1}(\boldsymbol{\theta}_A) \mathbf{J}(\boldsymbol{\theta}_A) \mathbf{C}^{-1}(\boldsymbol{\theta}_A)$$



# Classes of Cramér-Rao Lower Bounds





# Outline



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- Closing remarks

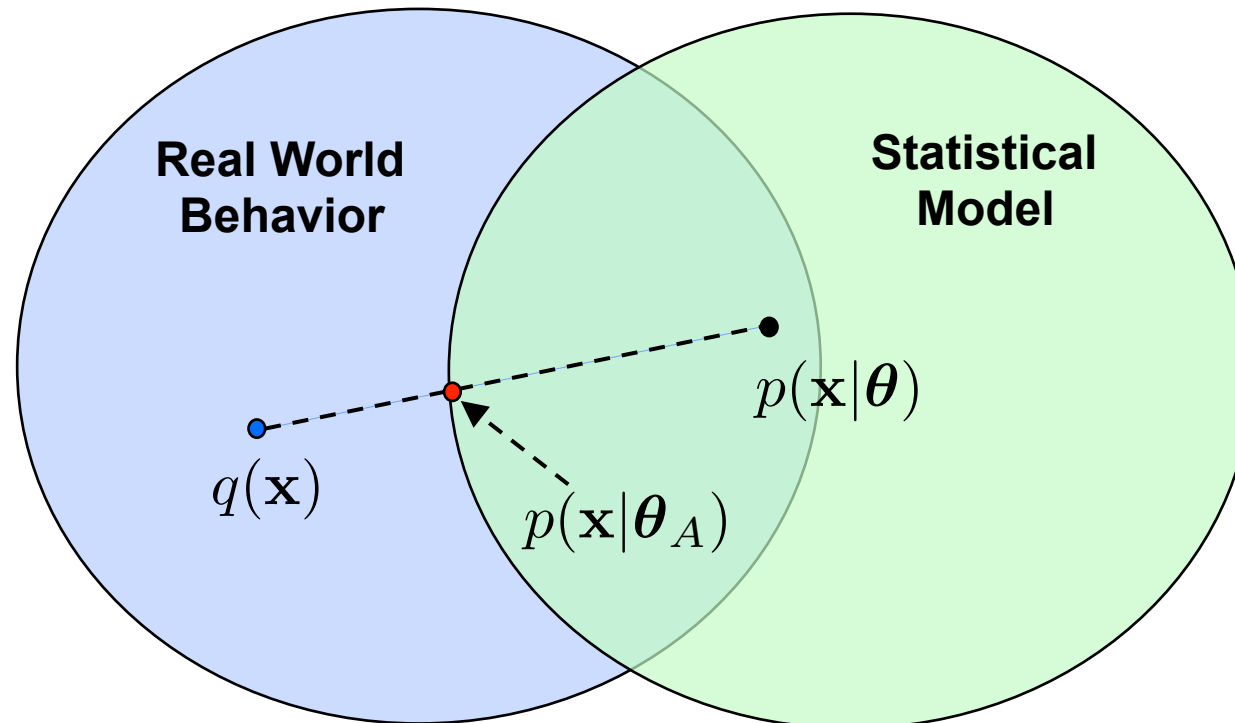


# Akshay Outline



- • **Introduction**
- **Communications Data Model**
- **Constrained Misspecified Cramer-Rao Bound**
- **Numerical Results**
- **Summary**

- Model Misspecification



– Bounds on accuracy in estimating parameter  $\boldsymbol{\theta}$ .



# Introduction



- **GOAL**: Develop **bounds** on parameter estimation performance in a **communication link** under **model misspecification**.

- **Model misspecification:**

Assumed model  $\neq$  True Model

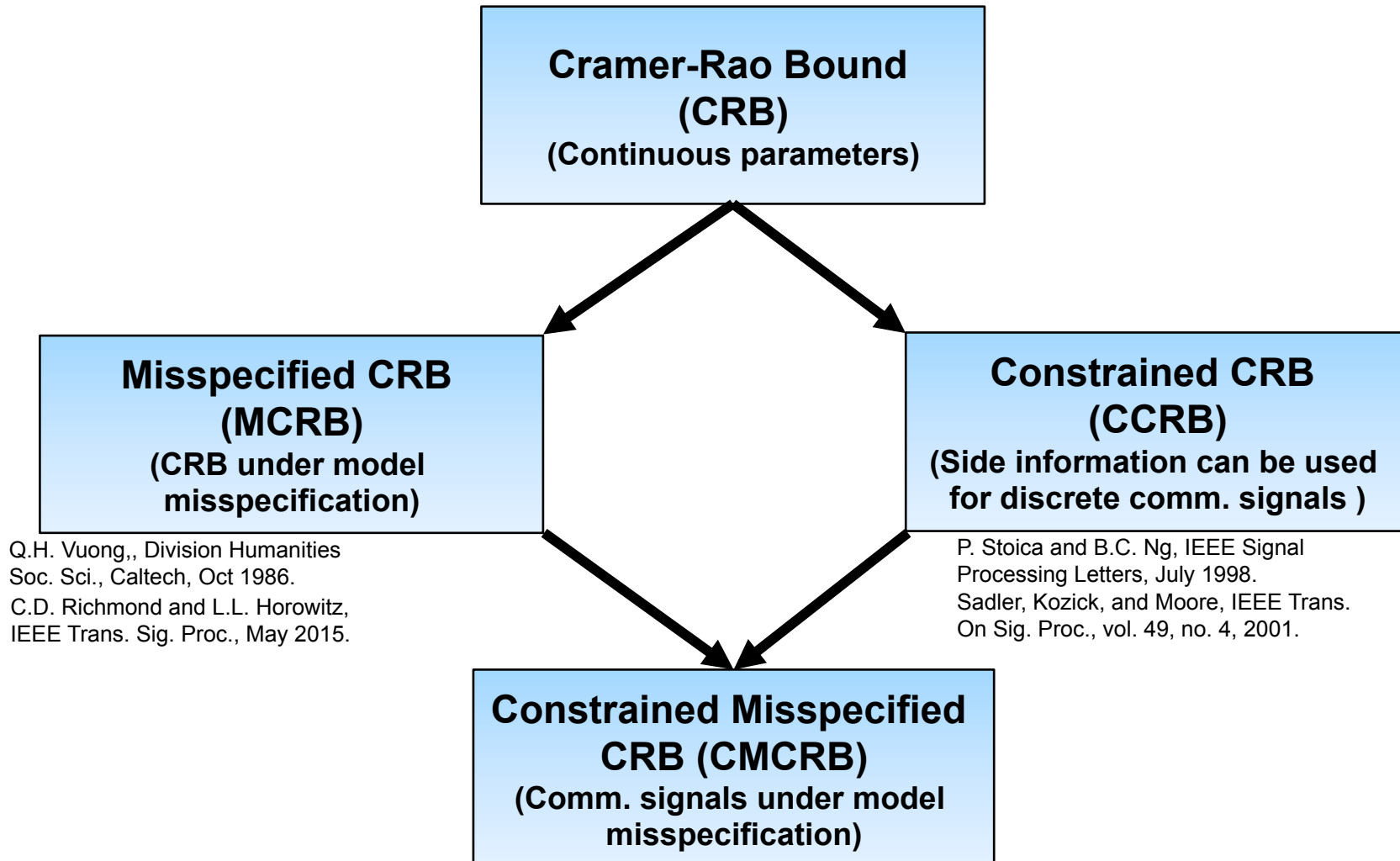
- **Cramer-Rao bound**  $\implies$  **CONTINUOUS PARAMETER.**

- **PROBLEM**:

**Communication signals**  $\implies$  **Discrete symbols**  
(Finite parameter space)



# Cramer-Rao Lower Bound



Q.H. Vuong,, Division Humanities Soc. Sci., Caltech, Oct 1986.  
C.D. Richmond and L.L. Horowitz, IEEE Trans. Sig. Proc., May 2015.

P. Stoica and B.C. Ng, IEEE Signal Processing Letters, July 1998.  
Sadler, Kozick, and Moore, IEEE Trans. On Sig. Proc., vol. 49, no. 4, 2001.

S. Fortunati, F. Gini, M.S. Greco, IEEE Signal Processing Letters, vol.23, no. 5, 2016.





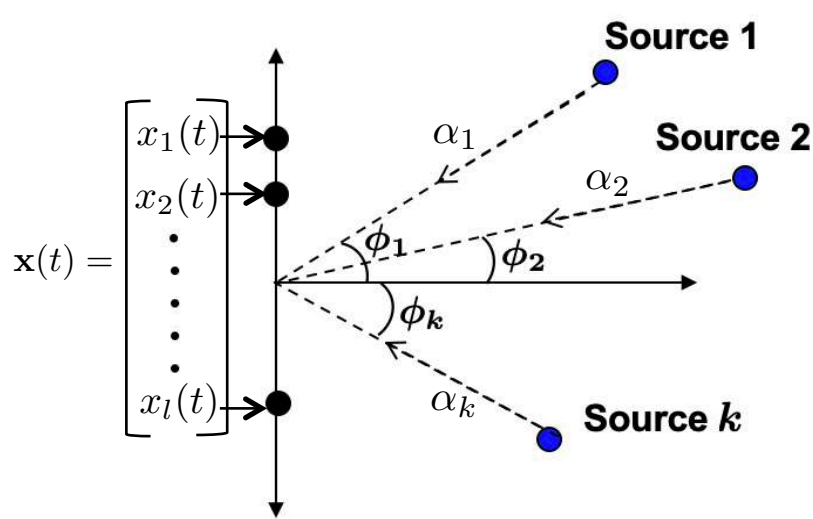
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# Flat-fading Data Model



- $l$  sensors and  $k$  sources.

- $\phi_i$ : Angles of arrival,  $\phi = [\phi_1, \dots, \phi_k]^T$

- $\alpha_i$ : Channel gains,  $\alpha = [\alpha_1, \dots, \alpha_k]^T$

- $\mathbf{a}(\phi_i)$ : Steering vectors

- $s_i(t)$ : Comm. signal from source  $i$  at time  $t$ ,  $t = 1, \dots, N$ .  
 $\mathbf{s}(t) = [s_1(t), \dots, s_k(t)]^T$

- **Flat-fading model:** Channel gains  $\implies$  constant over time,  
 Received signal  $\mathbf{x}(t)$ :  $(\alpha_i(t) = \alpha_i)$

$$\mathbf{x}(t) = \sum_{i=1}^k \mathbf{a}(\phi_i) \alpha_i s_i(t) + \mathbf{n}(t) = \mathbf{A}(\phi) \mathbf{\Delta}(\alpha) \mathbf{s}(t) + \mathbf{n}(t)$$

$\mathcal{CN}(0, \mathbf{R})$  n(t)



# Flat-fading Data Model

$$\begin{aligned}
 \bullet \quad \mathbf{x}(t) &= \begin{bmatrix} x_1(t) \\ x_2(t) \\ \vdots \\ x_l(t) \end{bmatrix}_{l \times 1} = \begin{bmatrix} & & \mathbf{A}(\phi) & & \\ & & | & & \\ \mathbf{a}(\phi_1) & \cdots & | & & \\ & & | & & \\ & & \mathbf{a}(\phi_k) & & \\ & & | & & \\ & & & & \mathbf{\Delta}(\alpha) & \\ & & & & | & \\ \alpha_1 & 0 & \cdots & 0 & \\ 0 & \alpha_2 & & \vdots & \\ \vdots & & & \ddots & 0 \\ 0 & \cdots & 0 & 0 & \alpha_k \end{bmatrix}_{l \times k} \cdot \begin{bmatrix} s_1(t) \\ s_2(t) \\ \vdots \\ s_k(t) \end{bmatrix}_{k \times 1} + \begin{bmatrix} n_1(t) \\ n_2(t) \\ \vdots \\ n_l(t) \end{bmatrix}_{l \times 1} \\
 &= \mathbf{A}(\phi) \mathbf{\Delta}(\alpha) \mathbf{s}(t) + \boxed{\mathbf{n}(t)} \longleftarrow \mathcal{CN}(\mathbf{0}, \mathbf{R})
 \end{aligned}$$

- $N$  such snapshots are stacked to form the data vector  $\tilde{\mathbf{x}}$ .

$$\bullet \quad \tilde{\mathbf{x}} = \begin{bmatrix} \mathbf{x}(1) \\ \vdots \\ \mathbf{x}(N) \end{bmatrix} = \begin{bmatrix} \mathbf{A}(\phi) \mathbf{\Delta}(\alpha) \mathbf{s}(1) \\ \vdots \\ \mathbf{A}(\phi) \mathbf{\Delta}(\alpha) \mathbf{s}(N) \end{bmatrix} + \begin{bmatrix} \mathbf{n}(1) \\ \vdots \\ \mathbf{n}(N) \end{bmatrix} = \boldsymbol{\mu} + \boxed{\tilde{\mathbf{n}}} \longleftarrow \mathcal{CN}(\mathbf{0}, \underbrace{\mathbf{I}_N \otimes \mathbf{R}}_{=\tilde{\mathbf{R}}})$$

$$\tilde{\mathbf{x}} \sim \mathcal{CN}(\boldsymbol{\mu}, \tilde{\mathbf{R}})$$



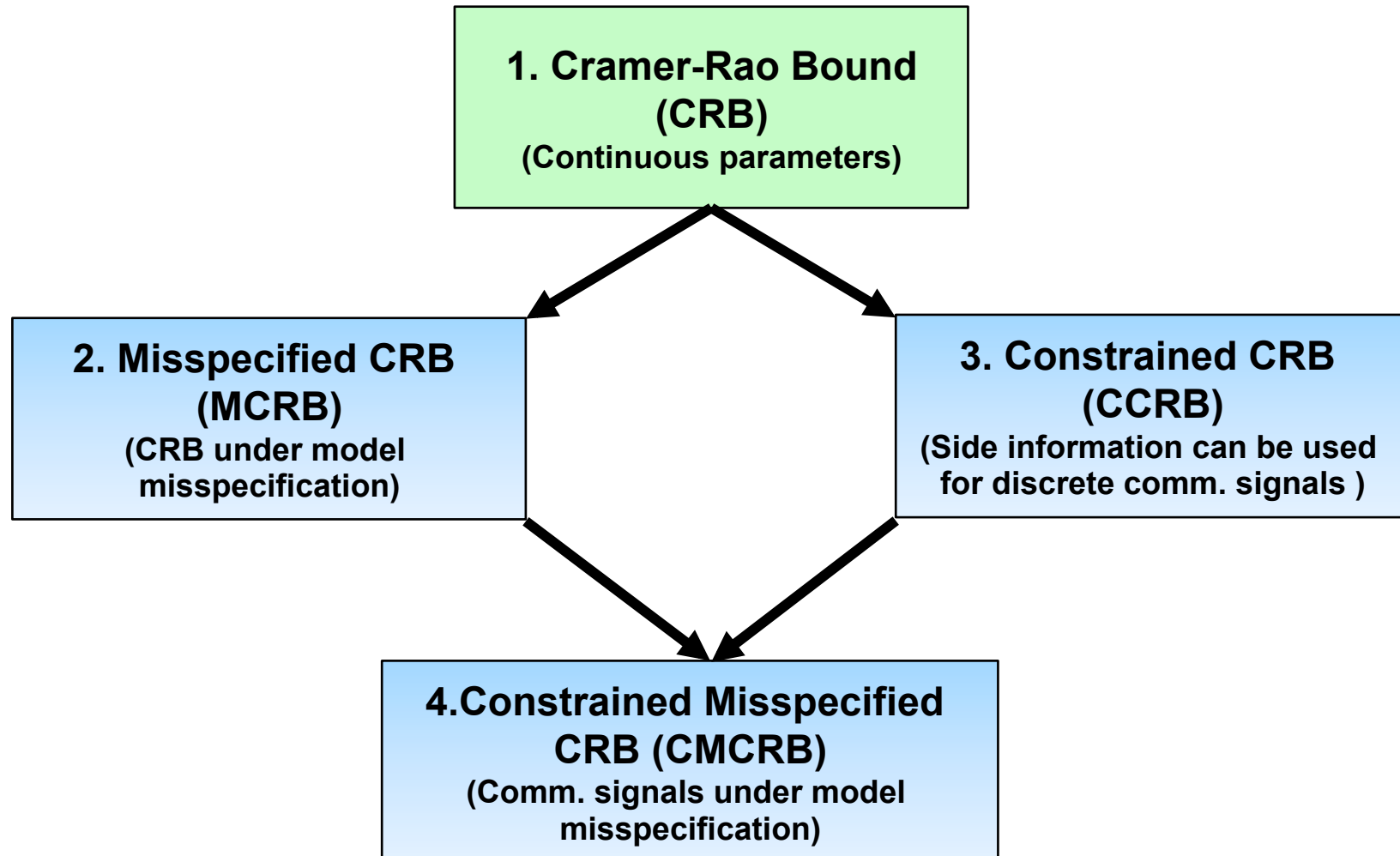
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# Cramer-Rao Lower Bound



S. Fortunati, F. Gini, M.S. Greco, "The constrained misspecified Cramer-Rao bound", IEEE Signal Processing Letters, vol.23, no. 5, 2016.



# Unconstrained Cramer-Rao Bound



- **Parameter vector**  $\boldsymbol{\theta} = [\theta_1, \dots, \theta_M]^T = [\tilde{\mathbf{s}}; \tilde{\mathbf{s}}^*; \boldsymbol{\alpha}; \boldsymbol{\alpha}^*; \boldsymbol{\phi}]^T$ .

$$\tilde{\mathbf{s}} = [\mathbf{s}(1); \mathbf{s}(2); \dots; \mathbf{s}(N)]^T.$$

$$\begin{aligned} \boldsymbol{\alpha} &= [\alpha_1, \dots, \alpha_k]^T \\ \boldsymbol{\phi} &= [\phi_1, \dots, \phi_k]^T \\ \mathbf{s}(t) &= [s_1(t), \dots, s_k(t)]^T \end{aligned}$$

- $\tilde{\mathbf{x}} \sim \mathcal{CN}(\boldsymbol{\mu}(\boldsymbol{\theta}), \tilde{\mathbf{R}}) = p_{\tilde{\mathbf{x}}|\boldsymbol{\theta}}$

$\implies$  Only the mean is characterized by  $\boldsymbol{\theta}$ .

- **Unconstrained Fisher Information Matrix (FIM)  $\mathbf{J}(\boldsymbol{\theta})$**

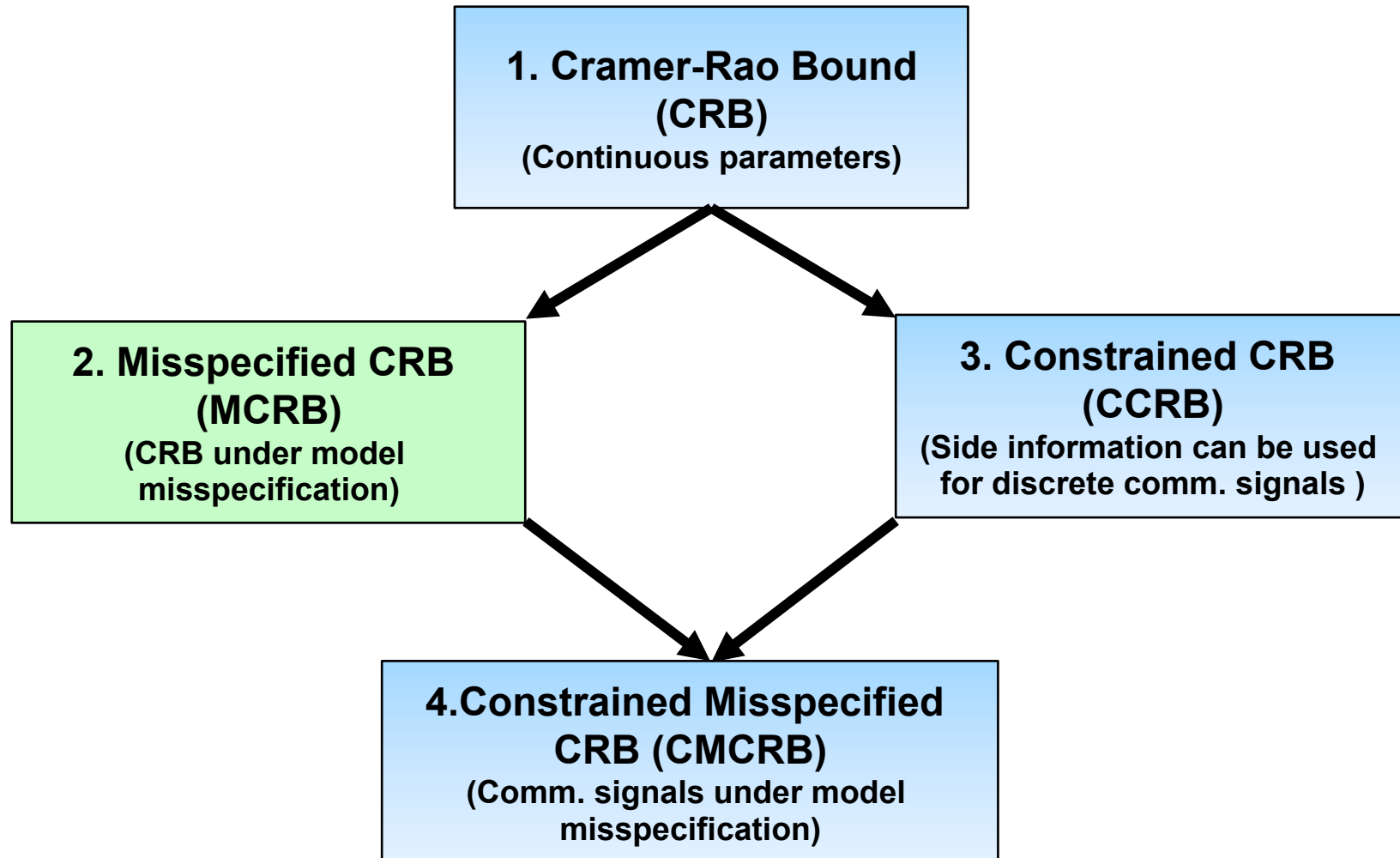
$$\mathbf{J}(\boldsymbol{\theta}) = \frac{\partial \boldsymbol{\mu}^*}{\partial \boldsymbol{\theta}^*} \tilde{\mathbf{R}}^{-1} \left( \frac{\partial \boldsymbol{\mu}}{\partial \boldsymbol{\theta}} \right)^T + \frac{\partial \boldsymbol{\mu}}{\partial \boldsymbol{\theta}} \left( \tilde{\mathbf{R}}^{-1} \right)^* \left( \frac{\partial \boldsymbol{\mu}^*}{\partial \boldsymbol{\theta}^*} \right)^T$$

- **Cramer-Rao Bound:**

$$\mathbb{E} \left[ \left( \hat{\boldsymbol{\theta}} - \boldsymbol{\theta} \right) \left( \hat{\boldsymbol{\theta}} - \boldsymbol{\theta} \right)^H \right] \geq \mathbf{J}^{-1}(\boldsymbol{\theta})$$



# Cramer-Rao Lower Bound





# Misspecified Cramer-Rao Bound



- **Assumed flat-fading model:**  $\tilde{\mathbf{x}} \sim \mathcal{CN}(\boldsymbol{\mu}(\boldsymbol{\theta}), \tilde{\mathbf{R}}) = p_{\tilde{\mathbf{x}}|\boldsymbol{\theta}}$
  - **True data model:**  $\tilde{\mathbf{x}} \sim \mathcal{CN}(\mathbf{d}, \tilde{\mathbf{R}}) = q_{\tilde{\mathbf{x}}}$
- $\tilde{\mathbf{R}}$  is assumed to be known and correct.

$$\boldsymbol{\theta}_A = \arg \min_{\boldsymbol{\theta}} D(q_{\tilde{\mathbf{x}}} || p_{\tilde{\mathbf{x}}|\boldsymbol{\theta}})$$

- **Complexified Misspecified Fisher Information Matrix (MFIM)**

$$\mathbf{J}(\boldsymbol{\theta}) = \frac{\partial \boldsymbol{\mu}^*}{\partial \boldsymbol{\theta}^*} \tilde{\mathbf{R}}^{-1} \left( \frac{\partial \boldsymbol{\mu}}{\partial \boldsymbol{\theta}} \right)^T + \frac{\partial \boldsymbol{\mu}}{\partial \boldsymbol{\theta}^*} \left( \tilde{\mathbf{R}}^{-1} \right)^* \left( \frac{\partial \boldsymbol{\mu}^*}{\partial \boldsymbol{\theta}} \right)^T$$

for  $\tilde{\mathbf{R}}$  assumed to be known and correct (same as unconstrained FIM for this case).





# Misspecified Cramer-Rao Bound



- Complexified Average Hessian  $C(\theta)$

$$[C(\theta)]_{i,j} \triangleq - \left[ \frac{\partial \mu^*(\theta)}{\partial \theta_i^*} \right]^T \tilde{\mathbf{R}}^{-1} \frac{\partial \mu(\theta)}{\partial \theta_j} - \left[ \frac{\partial \mu^*(\theta)}{\partial \theta_j} \right]^T \tilde{\mathbf{R}}^{-1} \frac{\partial \mu(\theta)}{\partial \theta_i^*} \\ + \left[ \frac{\partial^2 \mu^*(\theta)}{\partial \theta_i^* \partial \theta_j} \right]^T \tilde{\mathbf{R}}^{-1} \delta \mu(\theta) + \delta \mu^H(\theta) \tilde{\mathbf{R}}^{-1} \frac{\partial^2 \mu^*(\theta)}{\partial \theta_i^* \partial \theta_j}$$

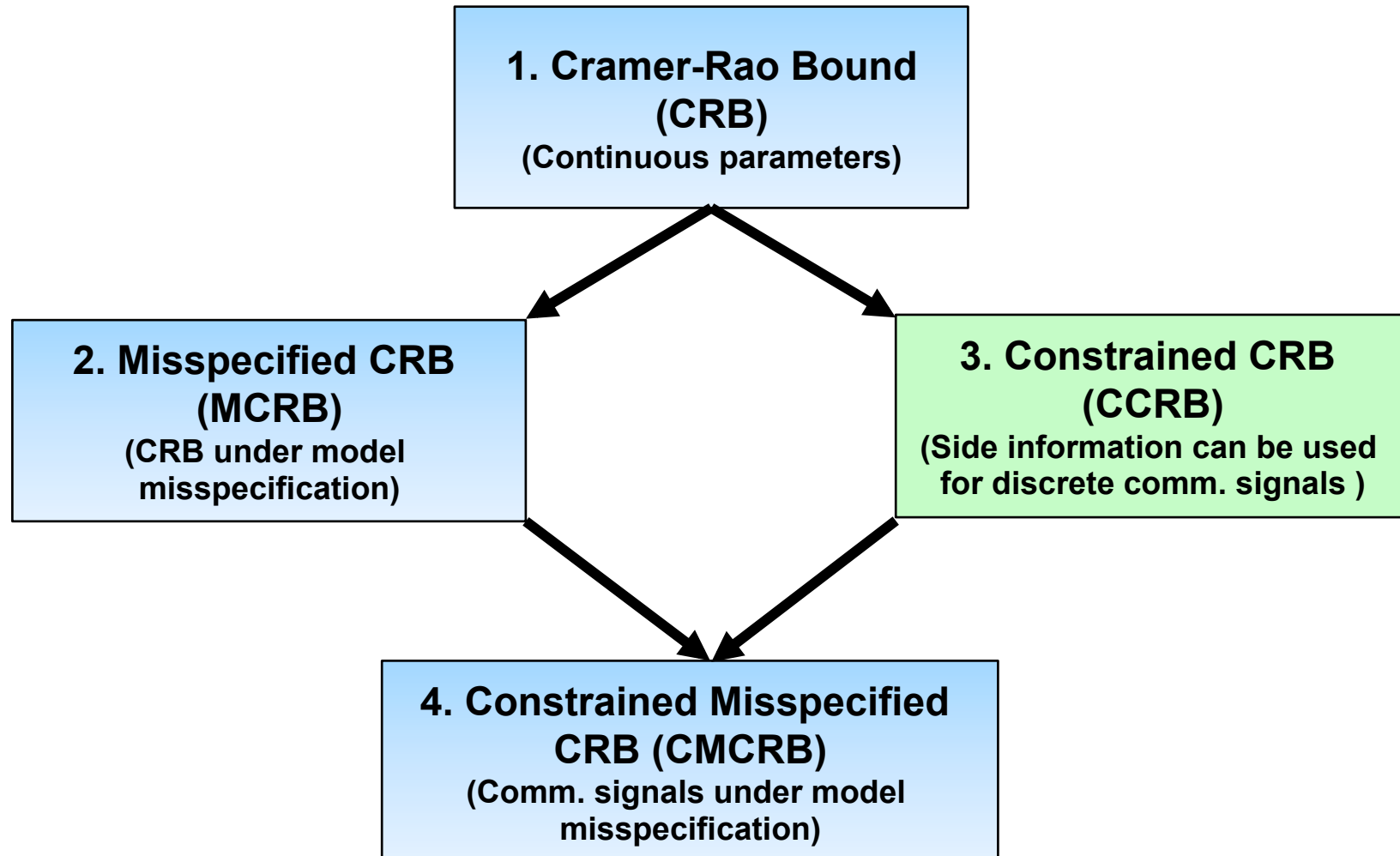
- Misspecified CRB

$$\theta_A = \arg \min_{\theta} D(q_{\tilde{\mathbf{x}}} \parallel p_{\tilde{\mathbf{x}}|\theta})$$

$$\mathbb{E} \left[ \left( \hat{\theta} - \theta_A \right) \left( \hat{\theta} - \theta_A \right)^H \right] \geq \mathbf{C}^{-1}(\theta_A) \mathbf{J}(\theta_A) \mathbf{C}^{-1}(\theta_A)$$



# Cramer-Rao Lower Bound



S. Fortunati, F. Gini, M.S. Greco, "The constrained misspecified Cramer-Rao bound", IEEE Signal Processing Letters, vol.23, no. 5, 2016.



# Constrained Cramer-Rao Bound



1. **Given**  $m$  constraints on  $\theta$ :  $\mathbf{f}(\theta) = [f_1(\theta), \dots, f_m(\theta)]^T = \mathbf{0}_{m \times 1}$

2. **Gradient matrix**  $\mathbf{F}(\theta)$ :  $\mathbf{F}(\theta) = \left[ \frac{\partial \mathbf{f}(\theta)}{\partial \theta^*} \right]^T$

3. **There exists a unitary matrix**  $\mathbf{U}$  such that

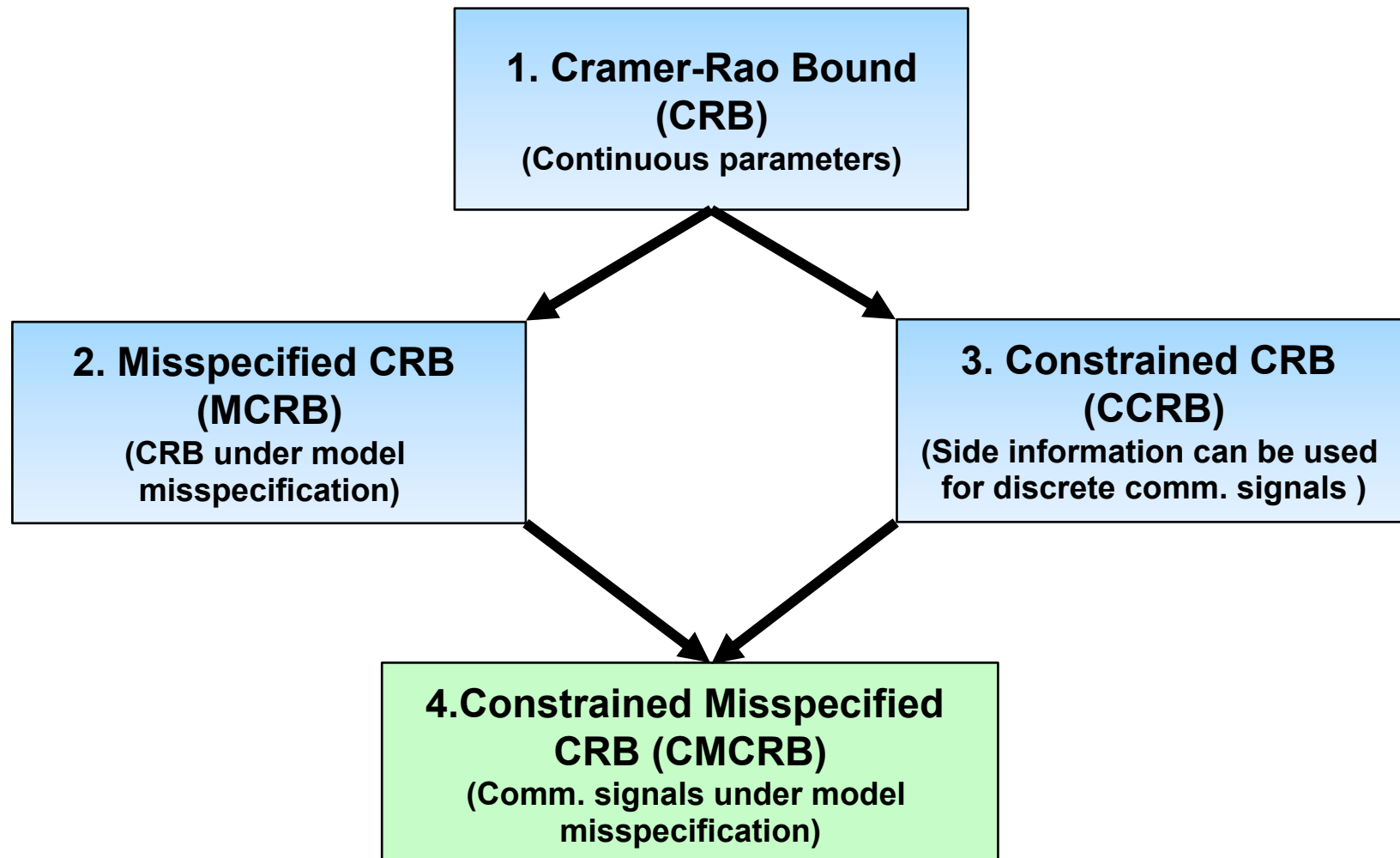
$$\mathbf{F}(\theta)\mathbf{U} = \mathbf{0}_{m \times (2Nk+3k-m)}$$

4. **CCRB**

$$\mathbb{E} \left[ \left( \hat{\theta} - \theta \right) \left( \hat{\theta} - \theta \right)^H \right] \geq \mathbf{U} \left( \mathbf{U}^H \mathbf{J}(\theta) \mathbf{U} \right)^{-1} \mathbf{U}^H$$



# Cramer-Rao Lower Bound



S. Fortunati, F. Gini, M.S. Greco, "The constrained misspecified Cramer-Rao bound", IEEE Signal Processing Letters, vol.23, no. 5, 2016.



# Constrained Misspecified Cramer-Rao Bound



- **Misspecified CRB (MCRB):**

$$\mathbb{E} \left[ \left( \hat{\boldsymbol{\theta}} - \boldsymbol{\theta}_A \right) \left( \hat{\boldsymbol{\theta}} - \boldsymbol{\theta}_A \right)^H \right] \geq \mathbf{C}^{-1}(\boldsymbol{\theta}_A) \mathbf{J}(\boldsymbol{\theta}_A) \mathbf{C}^{-1}(\boldsymbol{\theta}_A)$$

- **Constrained CRB (CCRB):**

$$\mathbb{E} \left[ \left( \hat{\boldsymbol{\theta}} - \boldsymbol{\theta} \right) \left( \hat{\boldsymbol{\theta}} - \boldsymbol{\theta} \right)^H \right] \geq \mathbf{U}(\mathbf{U}^H \mathbf{J}(\boldsymbol{\theta}) \mathbf{U})^{-1} \mathbf{U}^H$$

- **Constrained Misspecified CRB (CMCRB):**

$$\mathbb{E} \left[ \left( \hat{\boldsymbol{\theta}} - \boldsymbol{\theta}_A \right) \left( \hat{\boldsymbol{\theta}} - \boldsymbol{\theta}_A \right)^H \right] \geq \mathbf{U}(\mathbf{U}^H \mathbf{C}(\boldsymbol{\theta}_A) \mathbf{U})^{-1} \mathbf{U}^H \\ \times \mathbf{J}(\boldsymbol{\theta}_A) \mathbf{U}(\mathbf{U}^H \mathbf{C}(\boldsymbol{\theta}_A) \mathbf{U})^{-1} \mathbf{U}^H$$



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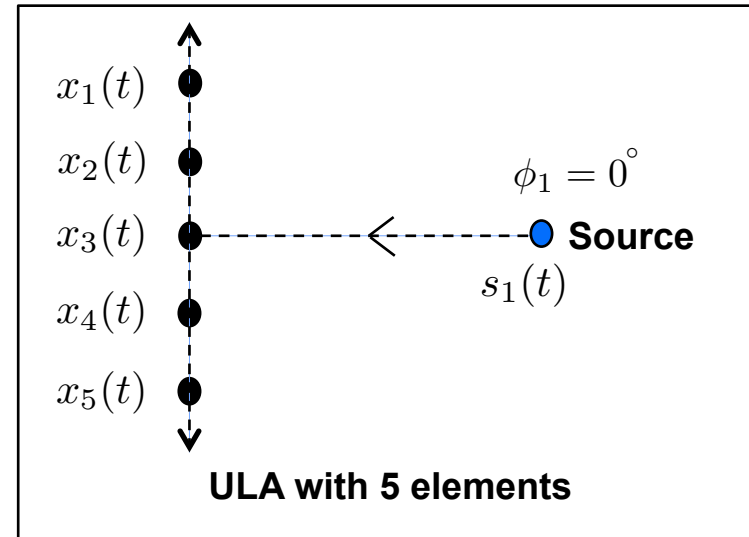
# Simulation Setup



- **Single source**  $\Rightarrow$   $k = 1$

- **Angle of arrival**  $\Rightarrow$   $\phi_1 = 0^\circ$

- **Uniform Linear Array with 5 sensors**  $\Rightarrow$   $l = 5$



- **BPSK modulation with equal probability**  $\Rightarrow$   $s_1(t) = \pm 1$ ,  $t = 1, \dots, N = 100$

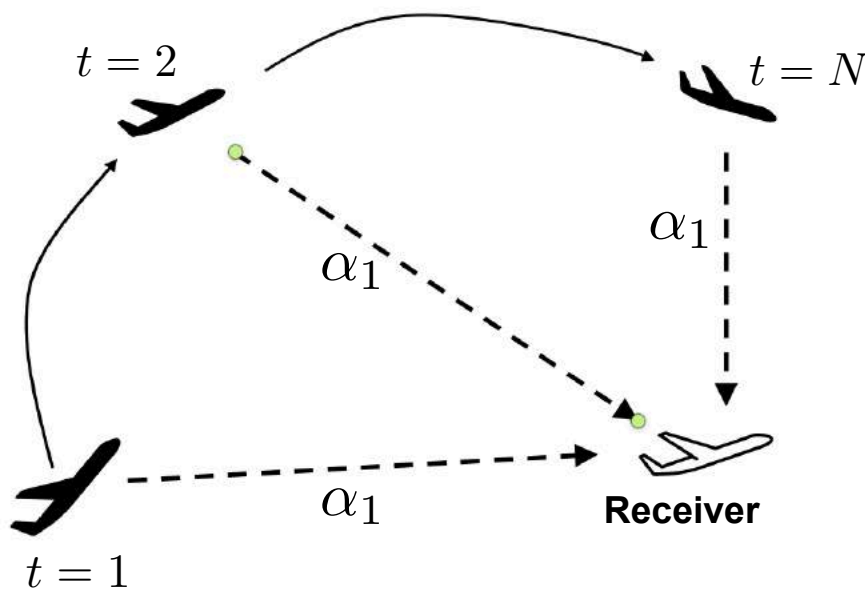
- **White Gaussian Noise**  $\Rightarrow$   $\tilde{\mathbf{R}} = \sigma^2 \mathbf{I}$



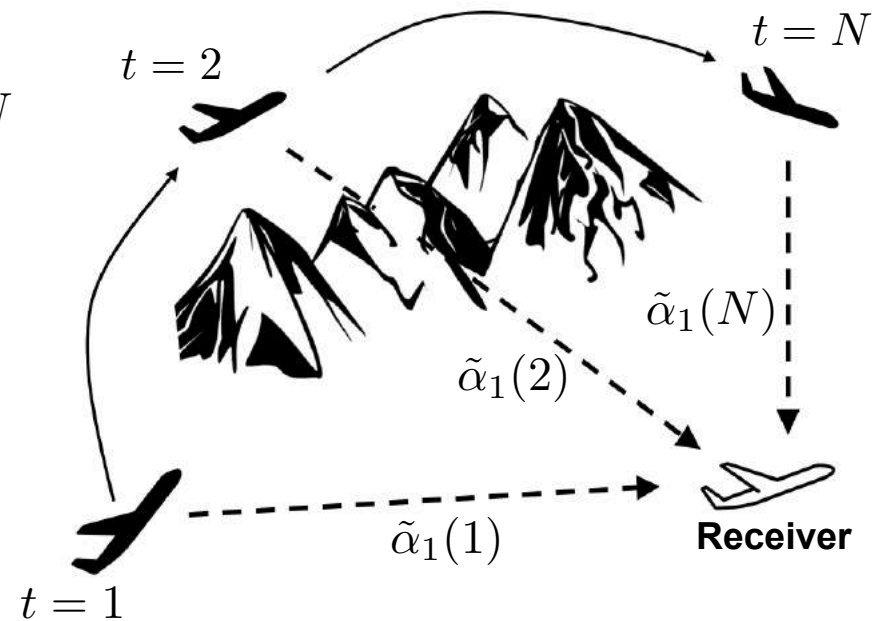
# Model Misspecification – Dynamic Channel



**Assumed Model:  
Constant channel gains**



**True Model:  
Time-varying channel gains**







# Model Misspecification – Dynamic Channel



- **Assumed model**  $\implies \alpha_1(t) = \alpha_1$  (**Constant Channel Gain**)

$$\tilde{\mathbf{x}} \sim \mathcal{CN}(\boldsymbol{\mu}(\boldsymbol{\theta}), \tilde{\mathbf{R}}) = p_{\tilde{\mathbf{x}}|\boldsymbol{\theta}} \implies \boldsymbol{\mu}(\boldsymbol{\theta}) = \begin{bmatrix} \alpha_1 s_1(1) \mathbf{a}(\phi_1) \\ \vdots \\ \alpha_1 s_1(N) \mathbf{a}(\phi_1) \end{bmatrix}$$

- **True Model**  $\implies$  **Channel Gains Vary with time**

$$\tilde{\mathbf{x}} \sim \mathcal{CN}(\mathbf{d}, \tilde{\mathbf{R}}) = q_{\tilde{\mathbf{x}}} \implies \mathbf{d} = \begin{bmatrix} \tilde{\alpha}_1(1) s_1(1) \mathbf{a}(\phi_1) \\ \vdots \\ \tilde{\alpha}_1(N) s_1(N) \mathbf{a}(\phi_1) \end{bmatrix}$$

$$\boldsymbol{\theta}_A = \arg \min_{\boldsymbol{\theta}} D(q_{\tilde{\mathbf{x}}} || p_{\tilde{\mathbf{x}}|\boldsymbol{\theta}})$$



# Model Misspecification – Dynamic Channel



- It can be shown that

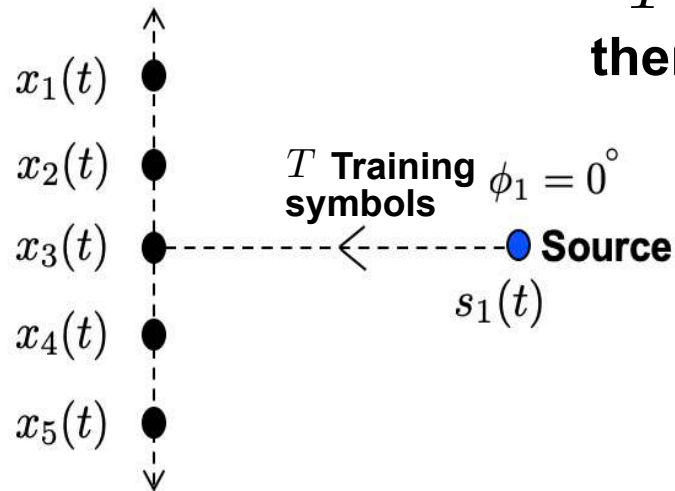
$$\boldsymbol{\theta}_A = [s_1(1), \dots, s_1(N), s_1^*(1), \dots, s_1^*(N), \alpha_{1,A}, \alpha_{1,A}^*, \phi_{1,A}]^T$$

- $$\phi_{1,A} = \arg \max_{\phi} \frac{|\mathbf{a}^H(\phi) \tilde{\mathbf{R}}^{-1} \mathbf{a}^H(\phi_1)|^2}{\mathbf{a}^H(\phi) \tilde{\mathbf{R}}^{-1} \mathbf{a}^H(\phi)} \cdot \frac{\left| \sum_{i=1}^T |s_1(i)|^2 \tilde{\alpha}_1(i) \right|^2}{\sum_{i=1}^T |s_1(i)|^2}$$

- $$\alpha_{1,A} = \frac{\mathbf{a}^H(\phi_{1,A}) \tilde{\mathbf{R}}^{-1} \mathbf{a}^H(\phi_1)}{\mathbf{a}^H(\phi_{1,A}) \tilde{\mathbf{R}}^{-1} \mathbf{a}^H(\phi_{1,A})} \cdot \frac{\left| \sum_{i=1}^T |s_1(i)|^2 \tilde{\alpha}_1(i) \right|^2}{\sum_{i=1}^T |s_1(i)|^2}$$



# Semi-Blind Constraint for Communications Model



- $T$  training symbols available for source  $j$ , then the  $m = 2T$  complex constraints on  $\theta$  are:

$$\left. \begin{aligned} f_{2i-1}(\theta) &= s_j(i) - s_{ji} = 0 \\ f_{2i}(\theta) &= s_j^*(i) - s_{ji}^* = 0 \end{aligned} \right\} i = 1, \dots, T$$

- **Gradient Matrix**  $\mathbf{F}_j(\theta) = [\mathbf{I}_T \otimes \mathbf{E}_j, \quad \mathbf{0}_{2T \times (N-T)k}, \quad \mathbf{I}_T \otimes \mathbf{G}_j]$

where  $\mathbf{E}_j = \begin{bmatrix} \mathbf{0}_{1 \times k} \\ \mathbf{e}_j^T \end{bmatrix}$ ,  $\mathbf{G}_j = \begin{bmatrix} \mathbf{e}_j^T \\ \mathbf{0}_{1 \times k} \end{bmatrix}$  and  $\mathbf{e}_j^T = [0, \dots, 0, \underset{\substack{\uparrow \\ j^{th} \text{ position}}}{1}, 0, \dots, 0]_{1 \times k}$ .

- Null matrix  $\mathbf{U}$  can be computed such that  $\mathbf{F}(\theta)\mathbf{U} = \mathbf{0}_{m \times (2Nk+3k-m)}$ .



# Constrained Misspecified Cramer-Rao Bound



- Thus we have found  $\theta_A$  and  $\mathbf{U}$ .
- $\mathbf{J}(\theta)$  and average Hessian  $\mathbf{C}(\theta)$  derived in the paper.
- **Constrained Misspecified CRB:**

$$\mathbb{E} \left[ \left( \hat{\theta} - \theta_A \right) \left( \hat{\theta} - \theta_A \right)^H \right] \geq \mathbf{U} \left( \mathbf{U}^H \mathbf{C}(\theta_A) \mathbf{U} \right)^{-1} \mathbf{U}^H \\ \times \mathbf{J}(\theta_A) \mathbf{U} \left( \mathbf{U}^H \mathbf{C}(\theta_A) \mathbf{U} \right)^{-1} \mathbf{U}^H$$



# Numerical Results



- Assumed model:  $\alpha_1$  constant.

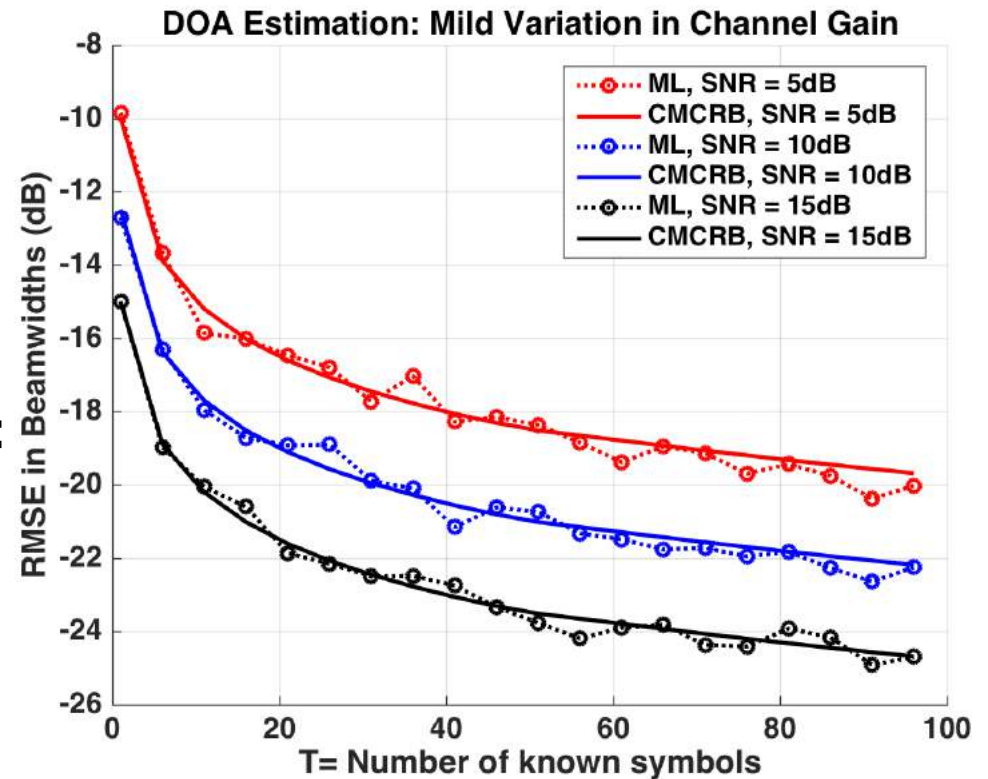
- True Model:

$$\tilde{\alpha}_1(t) = \begin{cases} e^{j100^\circ}, & t = 1, 2, \dots, 50 \\ e^{j113^\circ}, & t = 51, 52, \dots, 100. \end{cases}$$

- Maximum Likelihood Estimate:

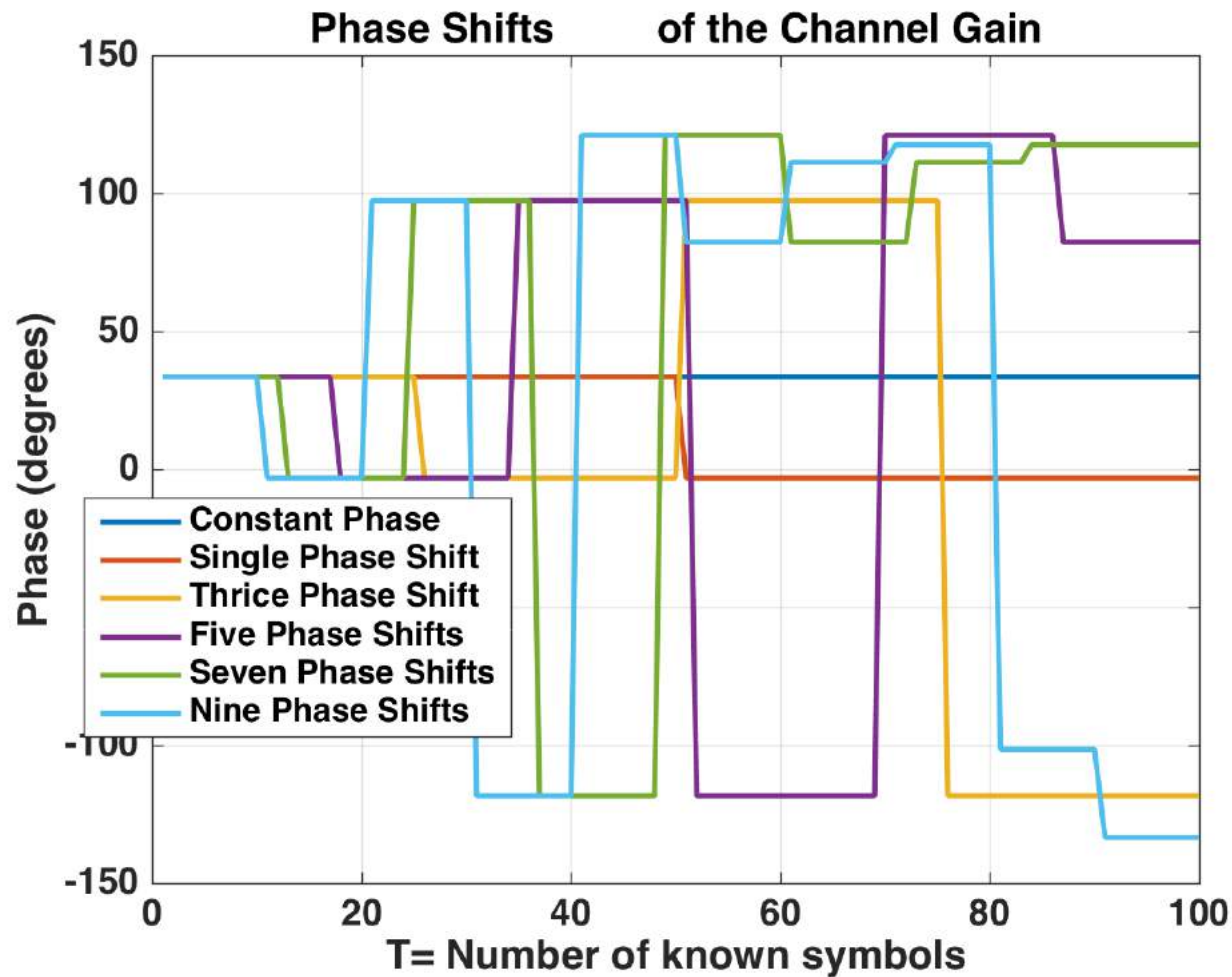
$$\hat{\phi}_{1,ML} = \arg \max_{\phi} \frac{|\mathbf{v}^H(\phi) \tilde{\mathbf{R}}^{-1} \tilde{\mathbf{x}}|^2}{\mathbf{v}^H(\phi) \tilde{\mathbf{R}}^{-1} \mathbf{v}(\phi)}$$

$$\mathbf{v}(\phi) = \begin{bmatrix} s_1(1)\mathbf{a}(\phi) \\ \vdots \\ s_1(N)\mathbf{a}(\phi) \end{bmatrix}$$



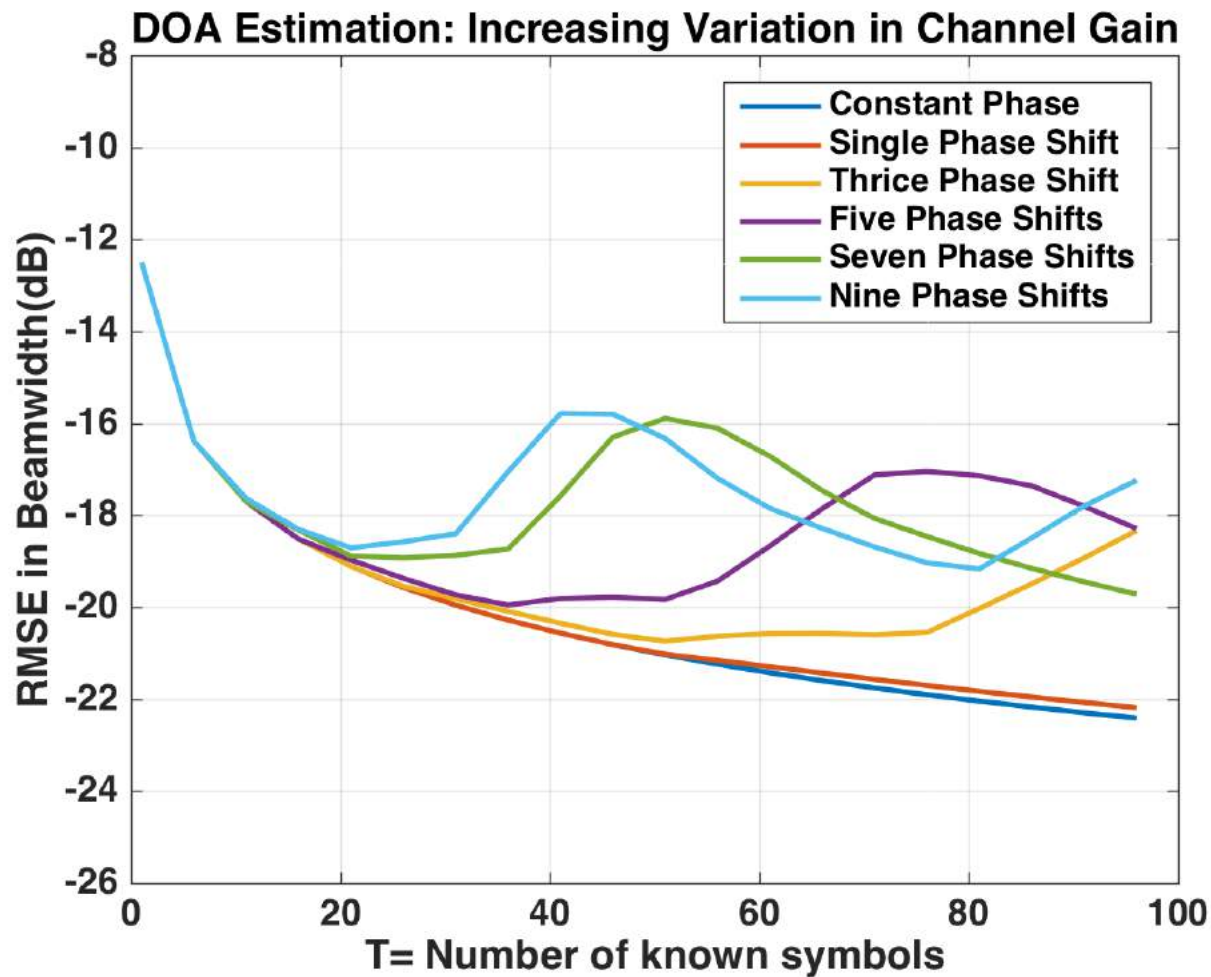


# Numerical Results





# Numerical Results





# Summary



- **Parameter estimation bounds** for a **communication link** under **model misspecification**.
- **Constrained Misspecified Cramer Rao Bound (CMCRB)**.
- **Dynamic Channel** – Bounds on angle of arrival when channel gains **vary with time** but are **assumed to be constant**.
- Effect on bounds when **dynamic nature** of channel is **varied**.
- Different forms of dynamic channels can be considered.





# Outline



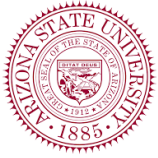
- Introduction
- Akshay's discussion
- • **Closing remarks**



# Closing Remarks



- **Initial results show encouraging agreement, and more complex channels can be considered**
  - **We welcome input from others here...**
    - Perhaps inform of important use cases to focus on
    - Perhaps inform of models that have been successfully employed, etc.
  - **Perhaps inform what can be assumed about TX/RX hardware?**
    - e.g. # antennas, bandwidth, modulation schemes, etc.
- **MCRB can help identify most essential aspects of modeling, e.g.**
  - **Determine which dynamics must be properly captured**
  - **versus which dynamics are less important**
- **CRB / MCRB can provide helpful reference points for performance comparisons**



# Backups





# Regularity Conditions: Allow Reverse Order of Integration and Differentiation



- By linearity of integration we have

$$\begin{aligned} E \left\{ (\hat{\theta} - \theta) \frac{\partial \ln p}{\partial \theta} \right\} &= \int (\hat{\theta} - \theta) \frac{\partial \ln p}{\partial \theta} p d\mathbf{x} \\ &= \int \hat{\theta} \frac{\partial \ln p}{\partial \theta} p d\mathbf{x} - \theta \int \frac{\partial \ln p}{\partial \theta} p d\mathbf{x} \end{aligned}$$

- Order reversal of integration / differentiation simplifies first term:

$$\begin{aligned} \int \hat{\theta} \frac{\partial \ln p}{\partial \theta} p d\mathbf{x} &= \int \hat{\theta} \cdot \frac{1}{p} \frac{\partial p}{\partial \theta} \cdot p d\mathbf{x} \\ &= \int \hat{\theta} \cdot \frac{\partial p}{\partial \theta} d\mathbf{x} = \frac{\partial}{\partial \theta} \int \hat{\theta} \cdot p d\mathbf{x} = \frac{\partial \theta}{\partial \theta} = 1 \end{aligned}$$

- Lastly, order reversal shows that second term vanishes:

$$\begin{aligned} \int \frac{\partial \ln p}{\partial \theta} \cdot p d\mathbf{x} &= \int \frac{1}{p} \frac{\partial p}{\partial \theta} \cdot p d\mathbf{x} \\ &= \int \frac{\partial p}{\partial \theta} d\mathbf{x} = \frac{\partial}{\partial \theta} \int p d\mathbf{x} = \frac{\partial}{\partial \theta} (1) = 0 \end{aligned}$$